### Dirac structures for infinite dimensional geometries and applications

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Plan:

Intro and definitions

infinite dimensions and reduction

Applications

# Intro

### brackets and constraints

(structure?) M ( ) symplectic / Poisson

lirac (~50): "The Hamiltonian method"

Ex: M constropic (1 dass)

Question: structure on M leading

to "Hamiltonian" type description



#### Relations between vectors and covectors



## Integrability: a background bracket

vector fields : Lie bracket 
$$X, Y \mapsto [X, Y]$$
  
fours : de Rhan d, Jie derivatives, contraction

T. Courant Weinstein Dorlman

$$(X, \alpha) \in \mathcal{X}(M) \oplus \mathcal{D}^{1}(M) \ni (Y, \beta)$$
$$[(X, \alpha), (Y, \beta)] = ([X, Y], L_{X}\beta - L_{Y}d\alpha)$$

Underlying geometry: foliation with presymplectic forms

L'inherits " Lie algebroid " structure  $M = \frac{1}{2 \cdot 2} \sum_{i=1}^{n} \sum_{i=1}^{n} \sum_{i=1}^{n} \frac{1}{2} \sum_{i$ 

# Examples

......

# old and new

• (n) symplectic : X ~ x ~  $\zeta_X \omega = \kappa$ Poisson  $\left(\{f,g\}=TT(df,dg)\right)$ :  $X \sim_{\chi} X \xrightarrow{\longrightarrow} X = TT(\chi,\bullet)$ 



Ruk: integrability axion reduces to dw=0 1 Jocobi for Sis  $L \cap T^{K}M = 0$ •  $L = g_{L}(W^{b}: TM \rightarrow T^{*}M) \xrightarrow{2}$  $L \cap TM = 0$  $L = g_{1}(T^{*}:T^{*}M \rightarrow TM) \iff$ 

• DESTM distribution:  $L = D \oplus D^0 (X \land X \in X \in D \land X \mid_{D} = 0)$ 

integrability of L to involutivity of D

$$X \sim \mathcal{A} \rightleftharpoons \exists \xi \in \mathcal{J}, \quad X = \mathcal{J} - \mathcal{J} \wedge \mathcal{A} = \frac{1}{2} (\mathcal{O} + \mathcal{O} \mathcal{R}) \cdot \mathcal{J}$$
  
Linfinitation  
Longingary action

$$I_{mfortant}: not "integrable" but "trusted - integrable"
with trust given by  $\emptyset \in S2^{3}(6)$  Cartan 3-form  
 $\emptyset = \frac{1}{12} k (OL, [OL, OL])$   
[Severa; Stabl, Weintern,...]  
trusts:  $[(X, \alpha), (Y, B)]_{\emptyset} = ([X, Y], L_{X} B - c_Y d\alpha + (y, b_Y \Phi)), dw_{0} = i_{0}^{*} H$$$

• In gentral, 
$$M \simeq (P, L_p) \longrightarrow induces L on M$$
  
 $X \sim X \ll J \approx J \approx (P), \quad x = i \star \alpha \wedge J_{xi}(X) \stackrel{p}{}_{ix}$   
Core : Smoothness  $\longrightarrow L$  Dirac on  $M$  ("Pull broke")  
 $x \mapsto L_x$ 



Uses dynamics and brackets  

$$\begin{array}{c} A \not x = f(x) \\ A \not x = f(x) \\ \hline \\ D_{anomics} : given L, H: M \rightarrow R \\ \hline \\ u(x) < M, [ x > 0 ] + dH[_{x > 0}] \\ \hline \\ u(x) < M, [ x > 0 ] + dH[_{x > 0}] \\ \hline \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = 0 \\ \hline \\ R \\ d(H(x < x)) = dH(x) = dH($$

#### Infinite dimensional structures

#### motivation and examples

$$\begin{array}{l} \mathcal{H} \quad \text{Hilbert spea} \quad \left( \mathcal{H}_{I}^{*} \stackrel{\sim}{}_{I} \mathcal{H} \right) \\ \hline \partial: \mathcal{D} \in \mathcal{H} \longrightarrow \mathcal{H} \quad \text{unbounded of nature} \\ \partial: \mathcal{D} \in \mathcal{H} \longrightarrow \mathcal{H} \quad \text{unbounded of nature} \\ \hline \partial: \mathcal{D} \in \mathcal{H} \implies \mathcal{H} \quad \mathcal{H$$

$$D_{i}f: a$$
 weak Poisson structure on  $M$  is a Dirac structure  
 $L \in TM \oplus T^*M$  such that  $L \cap TM = 0$ 

If U is a leaf of L weak Foisson => WO is weak symplectic strond (Wb = TO -> T\*O injective)

in examples with M x-dim, one has a candidate Rink: for Poisson {F,G} (def by x+>dx) best seen as Dirac st. but is not defined  $\forall f, g on M! \sim 5$ 

(H. Bursztyn)

Rules: at each x, the same operator  $\exists v = v \mid$ ,  $L_x \cong gi(3) \forall x$ 

• 
$$L \cap TM = 0$$
 but  $L + TM \neq TM \oplus Y^*M$   
 $(H^1 \in L^2 \text{ dense but } \neq) \longrightarrow \text{ We biology},$ 

• linear functional 
$$F_y(x) = \int_y y \cdot x$$
 for an by  $y \in H^{\prime}(S;R)$  is admissible  
for  $L$  and  
 $\{F_x, F_y\} = F_{x,y} = -F_{x,y}$   
Formally:  $\sum_i is induced$ 

Formally: 
$$\Sigma_{1}$$
 is induced  
by dual of Jie algebra  
 $H^{1}(S_{1}^{n}\mathbb{R}^{n}) \oplus \mathbb{R} =: Ih$   
 $E(x, 1), (7, 1)] = (0, S_{1} \times \cdot, \gamma)$   
 $M \cong (Ih)^{*}, h abelian$   
 $Jee$   
 $alg.$ 

# Reduction

similar to coisotropic reduction in symplectic geom

Pointime 
$$C_{\chi} \subseteq T_{\chi} M \oplus T_{\chi}^{*} M$$
  
Considulate for 4>:  $C_{\chi} \supseteq C_{\chi}^{\perp}$   
 $\Longrightarrow A_{\chi} := C_{\chi}/C_{\chi}^{\perp}$  inherits  $c_{\chi} >$  ("reduced Connect algebraid")  
if  $L_{\chi} \subseteq T_{\chi} M \oplus T_{\chi}^{*} M$  "Limm" Dirac and (so din)  $L_{\chi} + C_{\chi}$  close  
 $\Longrightarrow L_{\chi} = \frac{L_{\chi} \cap C_{\chi}}{L_{\chi} \cap C_{\chi}^{\perp}} \subseteq A_{\chi}$  Limen Dirac

$$\frac{\operatorname{Thm} 1 (AC, gulteri, heinrenken)}{\operatorname{Sh} M} \xrightarrow{} M_{G} \operatorname{principal} bruddeand  $\operatorname{G} = \operatorname{Lie} G \xrightarrow{P} \mathcal{K}(M) \oplus \operatorname{S}^{2}(M)$  x whended action  $\operatorname{FBurnstyn} (\operatorname{condentw} \operatorname{G} \operatorname{Subsenty})$   
 $\operatorname{S} \xrightarrow{} (\operatorname{G} \operatorname{M}, \operatorname{M}_{G}^{2})$  x whended action  $\operatorname{FBurnstyn} (\operatorname{condentw} \operatorname{G} \operatorname{G} \operatorname{Subsenty})$   
 $\operatorname{S} t: \langle P(3), \mathcal{C}(3) \rangle = 0 \land \operatorname{freesence} \operatorname{bradets} (\Xi, \Xi)$   
Then :  
 $\cdot \subset = \operatorname{S}(\operatorname{M} \times \operatorname{G})^{\perp}$  constrained and  $\operatorname{A} \longrightarrow \operatorname{M}$  is  $\operatorname{G} \operatorname{-basic}$  inducing  
 $\operatorname{Ared} := \operatorname{A}/_{\operatorname{G}} \operatorname{con} M_{\operatorname{G}}^{2} = \widetilde{\operatorname{M}}$  "reduced courset algeb"$$

$$\frac{\xi}{\xi}: suff. \quad Ls gr(\tilde{n}) \stackrel{\text{Pointon is } G - involuent \Rightarrow \tilde{T} \stackrel{\text{Pointon on } M/G}{\text{Pointon on } M/G} \stackrel{q: M \to M/G}{\tilde{T} (d\tilde{t}, d\tilde{g})^2 = T(\tilde{f} d\tilde{t}, \tilde{f} d\tilde{g})}$$

$$(hoose twide extension \quad P(\tilde{s}) = (\tilde{s}, n, 0) \longrightarrow \text{And} = \tilde{T} \stackrel{\text{Pointon on } M/G}{\text{Eq.}(T)} \stackrel{\text{Q}}{=} g_{\ell}(\tilde{T})$$

### Morphisms and reduction

Def morth. of fairs 
$$(A_{1}, L_{1}) - \frac{R_{2}}{R_{2}}(A_{2}, L_{2})$$
  
st:  $L_{2}|_{p(x_{1})} = \frac{R|_{(x_{1}, \beta(x_{1}))} \sim L_{1}|_{x_{1}}}{and this composition is transverse}$ 

For Lz = Cartan - Dirac,  $R:(TMOTM,TM) \rightarrow (A_H,L_H)$ which is full recovers quasi - Hamiltonian stares [ Alekseev, malkin, merwraken]

### An application

#### gauge theoretic constructions in dim 1 and 2



$$A \ni x \equiv A \longrightarrow \Im_{x} \equiv \Im_{A} : \Omega^{\circ}_{H_{r+1}} (I, h) \longrightarrow J_{x} A$$
 infiniterinal gauge  
 $M \to X \equiv A \longrightarrow \Im_{A} : \Omega^{\circ}_{H_{r+1}} (I, h) \longrightarrow J_{x} A$  infiniterinal gauge  
 $M \to M + \partial A M$  by  $M$ 

Det 
$$L_x = \{(\Im_x \Im_y \Pi_y; y; y \in \Omega^{\circ}_{H_{r+1}}(\Xi;h), \Im(0) = \Im(H)\} \in T_x A \oplus T_x A$$
  
Rof: L defines a Dirac structure on A which is weak - Pointon

Reduction: from infinite dimensional affine to finite dimensional non-linear

$$\frac{t}{t} \frac{t}{t} \frac{t}$$

1,7

$$= \sum_{i=1}^{n} \left\{ \left( \partial_A v_i, F_{v} \right) : v \in S^{i}_{H_{r+1}}(I, k) \right\}$$

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Surfaces WE Atiyah Bott 2 form TI	Triangle
$(M_{\Sigma} \rightarrow \mathcal{A}, W_{\Sigma})_{m_{Z}}$ Hamiltonian Stace for L Z reduction	(Maz-s 1 × 1 × 1 × 1 , Waz) multiplicatione properties relation of Castom - Dirac



#### "Hamiltonian" discretization of continuous systems



