

Lyapunov center theorem for Hamiltonian systems with symmetries

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Plan



D. Strzelecki.

Periodic solutions of symmetric Hamiltonian systems.

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- 1 Problem
- 2 Lypunov center theorem with symmetries
- 3 The ideas of proof
- 4 Applications

Symmetries in differential equations

Assume that Γ acts on \mathbb{R}^n by

$$\Gamma \times \mathbb{R}^n \ni (\gamma, z) \rightarrow \rho(\gamma)z \in \mathbb{R}^n,$$

where $\rho : \Gamma \rightarrow O(n) \subset GL(n)$ is a group homomorphism. $\gamma z := \rho(\gamma)z$.

The orbit of z_0 : $\Gamma(z_0) = \{\gamma z_0 : \gamma \in \Gamma\}$

The stabilizer of z_0 : $\Gamma_{z_0} = \{\gamma \in \Gamma : \gamma z_0 = z_0\}$

Invariant map: $f : \mathbb{R}^n \rightarrow \mathbb{R}$, $f(\gamma z) = f(z)$.

Equivariant map: $h : \mathbb{R}^n \rightarrow \mathbb{R}^n$, $h(\gamma z) = \gamma h(z)$.

$$\dot{z}(t) = h(z(t)) \tag{1}$$

$$\dot{z}(t) = \nabla f(z(t))$$

Remark

If $z(t)$ is a solution of (1) then $\gamma z(t)$ is a solution for any $\gamma \in \Gamma$.

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If $z(t)$ is a solution of (1) then $\gamma z(t)$ is a solution for any $\gamma \in \Gamma$.

What's the problem with symmetries?

$$\dot{x}(t) = h(x(t))$$

Noether's theorem - positive impact of symmetries

Every differentiable symmetry of the action of a physical system with conservative forces has a corresponding conservation law.

The problem

If $h(z_0) = 0$, then $\Gamma(z_0) \subset h^{-1}(0)$. Critical points are not isolated in general!

$$\Gamma(z_0) \approx \Gamma / \Gamma_{z_0}$$

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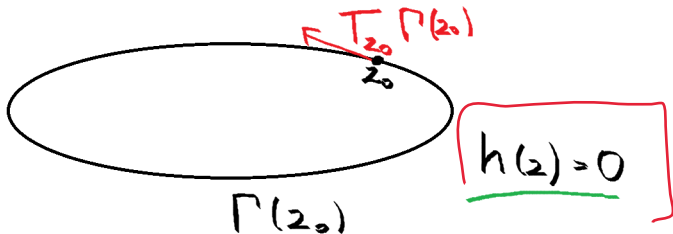
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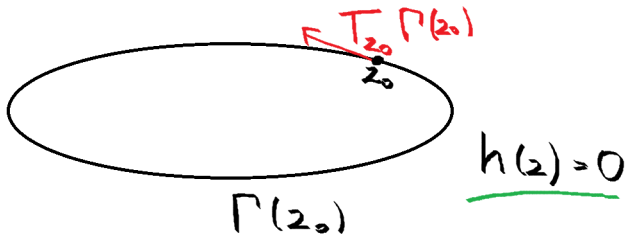
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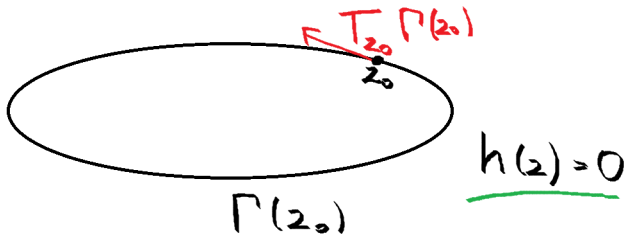
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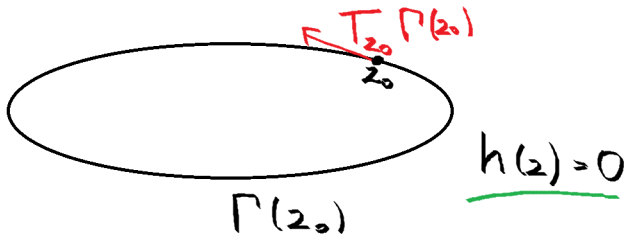
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Hamiltonian systems with symmetries

We assume that Γ acts unitary on \mathbb{R}^{2N} ($\rho : \Gamma \rightarrow U(N) = Sp(2n) \cap O(2n)$).

$$\dot{z}(t) = J\nabla H(z(t)), \quad (2)$$

where $J = \begin{bmatrix} 0 & Id_N \\ -Id_N & 0 \end{bmatrix}$, $z : \mathbb{R} \rightarrow \mathbb{R}^{2N}$ and $H \in C^2(\mathbb{R}^{2N}, \mathbb{R})$ is Γ -invariant. $\nabla H(z_0) = 0$.

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The goal

Prove the existence of periodic solutions of the system (2) in a neighborhood of stationary solution z_0 .

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Motivation - Liapunov center theorem



$$\dot{z}(t) = J\nabla H(z(t))$$

$$\nabla^2 H(0) > 0$$

Theorem

Let $H \in C^2(\mathbb{R}^{2N}, \mathbb{R})$, $\nabla H(0) = 0$. If $\sigma(J\nabla^2 H(0)) = \{\pm i\beta_1, \dots, \pm i\beta_m\}$ for $\beta_j \geq 0$ then for β_{j_0} satisfying $\beta_j/\beta_{j_0} \notin \mathbb{N}$ for $j \neq j_0$ there is a smooth two-dimensional manifold passing through 0 and intersecting each energy level near 0 in a periodic trajectory with minimal period near $2\pi/\beta_{j_0}$.

- Weinstein, 1973
- Moser, 1976
- Fadell i Rabinowitz, 1978
- Szulkin, 1994
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$|D^2 H(0)| \neq 0$

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Challenges

- Study $z_0 \in (\nabla H)^{-1}(0)$ such that $\dim \Gamma_{z_0} < \dim \Gamma$. Then the orbit $\Gamma(z_0)$ is at least one dimensional manifold and **critical points** from this orbit **are not isolated**.
- Allow a degeneracy of critical point $\det \nabla^2 H(z_0) = 0$ (in fact $\dim \ker \nabla^2 H(z_0) > \dim \Gamma(z_0)$).

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General assumptions

$$\dot{z}(t) = J\nabla H(z(t)) \quad (3)$$

- (A1) $H : \mathbb{R}^{2N} \rightarrow \mathbb{R}$ is a Γ -invariant Hamiltonian of the class C^2 ,
- (A2) $z_0 \in \mathbb{R}^{2N}$ is a critical point of H such that the isotropy group Γ_{z_0} is trivial,
- (A3) the orbit $\Gamma(z_0)$ is isolated in $(\nabla H)^{-1}(0)$,
- (A4) $\pm i\beta_1, \dots, \pm i\beta_m, 0 < \beta_m < \dots < \beta_1, m \geq 1$ are the purely imaginary eigenvalues of $J\nabla^2 H(z_0)$,
- (A5) $\deg(\nabla H|_{T_{z_0}^\perp \Gamma(z_0)}, B(z_0, \epsilon), 0) \neq 0$ for sufficiently small ϵ ,
- (A6) β_{j_0} is such that $\beta_j/\beta_{j_0} \notin \mathbb{N}$ for all $j \neq j_0$
- (A7) $m^- \left(\begin{bmatrix} -\lambda \nabla^2 H(z_0) & -J \\ J & -\lambda \nabla^2 H(z_0) \end{bmatrix} \right)$ changes at $\lambda = \frac{1}{\beta_{j_0}}$ when λ varies.


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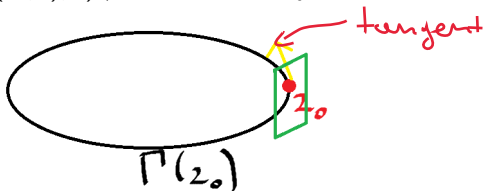
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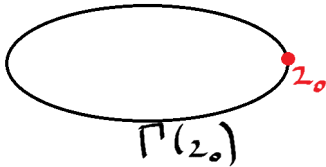
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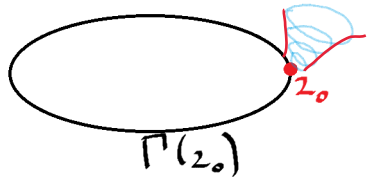
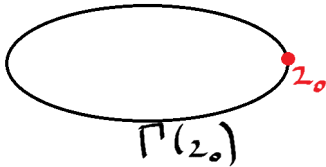
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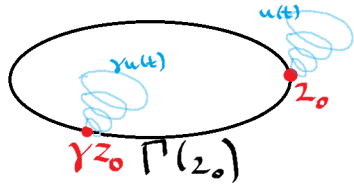
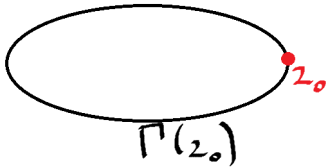
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Modifications

(A5) Brouwer degree $\deg_B(\nabla(H|_{T_{z_0}^\perp \Gamma(z_0)}), B^d(z_0, \epsilon), 0) \neq 0$ for sufficiently small ϵ and $d = \dim T_{z_0}^\perp \Gamma(z_0)$.

Fact

The assumption **(A5)** is satisfied for non-degenerate orbit i.e. under the assumption $\dim \Gamma(z_0) = \dim \ker \nabla^2 H(z_0)$.

(A7) $m^- \left(\begin{bmatrix} -\lambda \nabla^2 H(z_0) & -J \\ J & -\lambda \nabla^2 H(z_0) \end{bmatrix} \right)$ changes at $\lambda = \frac{1}{\beta_{j_0}}$ when λ varies.

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The assumption **(A7)** is implied by the condition

(A7') $m^+(\nabla^2 H(z_0)) > N$ or $m^-(\nabla^2 H(z_0)) > N$.

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The assumption **(A5)** is satisfied for non-degenerate orbit i.e. under the assumption $\dim \Gamma(z_0) \stackrel{!}{=} \dim \ker \nabla^2 H(z_0)$.

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Moreover, under **(A7')** the assumption **(A4)** is satisfied.

Modifications

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1/2 N

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Modifications

Theorem 2.

Under the assumptions **(A1)**, **(A2)**, **(A3)**, **(A5)** and **(A7')** there exists a connected family of non-stationary periodic solutions of the system $\dot{z}(t) = J\nabla H(z(t))$ emanating from the stationary solution z_0 with periods (not necessarily minimal) close to $2\pi/\beta_j$, where $i\beta_j$, $\beta_j > 0$ is some eigenvalue of $J\nabla^2 H(z_0)$.

Newtonian systems

$$\ddot{q}(t) = -\nabla U(q(t)) \quad (\text{UN})$$

$$H(p, q) = \frac{1}{2} \|p\|^2 + U(q)$$

$$\gamma(p, q) = (\gamma p, \gamma q) \text{ unitary action}$$

$$z_0 = (p_0, q_0)$$

- $\pm i\beta \in \sigma(J\nabla^2 H(z_0)) \Leftrightarrow \beta^2 \in \sigma(\nabla^2 U(q_0))$
- the assumption **(A7)** is always satisfied!
- what about **(A5)**?
 - non-degenerate orbit
 - q_0 is a minimum of the potential U

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Plan

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Variational problem

Periodic solutions of the system $\dot{z}(t) = J\nabla H(z(t))$



z_0

Variational problem

Periodic solutions of the system $\dot{z}(t) = J\nabla H(z(t))$
 \Updownarrow
 2π -periodic solutions of the parameterized system $\dot{z}(t) = \lambda J\nabla H(z(t))$
 \Updownarrow

$$z_0 \rightarrow \{z_0\} \times (0, \infty)$$

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 (3) Critical points of the functional $\Phi : \mathbb{H}^{1/2}(S^1, \mathbb{R}^{2N}) \times (0, \infty) \rightarrow \mathbb{R}$ given
 by $\Phi(z, \underline{\lambda}) = \frac{1}{2} \int_0^{2\pi} J\dot{z}(t) \cdot z(t) + \underline{\lambda} H(z(t)) dt$.

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WLOG we assume a growth condition $|\nabla H(z)| \leq a_1 + a_2|z|^s$ for some $a_1, a_2 > 0$ and $s \in [1, \infty)$.

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$$\Gamma \subset S^1 \rightarrow (\gamma, e^{i\theta}) \cdot z(t) \rightarrow \gamma \cdot z(t + \theta)$$

Fakt

The space $\mathbb{H}^{1/2}(S^1, \mathbb{R}^{2N})$ is an orthogonal representation of the group $G = \Gamma \times S^1$. Φ is G -invariant.

$$z_0 \rightarrow \{z_0\} \times (0, \infty) \rightarrow G(z_0) \times (0, \infty)$$

WLOG we assume a growth condition $|\nabla H(z)| \leq a_1 + a_2|z|^s$ for some $a_1, a_2 > 0$ and $s \in [1, \infty)$.

Bifurcation problem

$$\nabla_z \Phi(z, \lambda) = 0 \quad (\text{ZB})$$

Trivial set of solutions

$$\mathcal{T} = G(z_0) \times (0, \infty)$$

Let $\lambda_0 \in \{\frac{k}{\beta_j} : k \in \mathbb{N}\}$.

\mathbb{R}

$G(z_0) \times \{\lambda_+\}$

λ_+

λ_0

z_0

λ_-

$H^{1/2}(S^1, \mathbb{R}^{2N})$

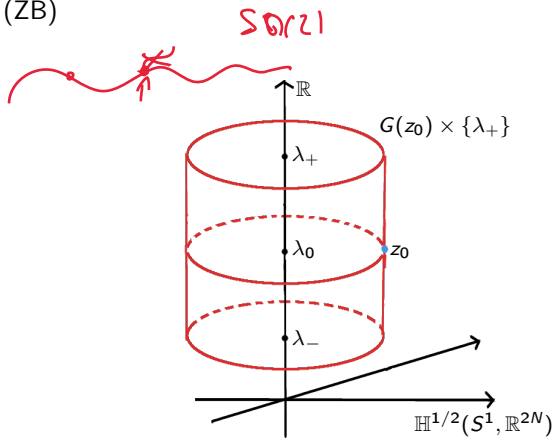
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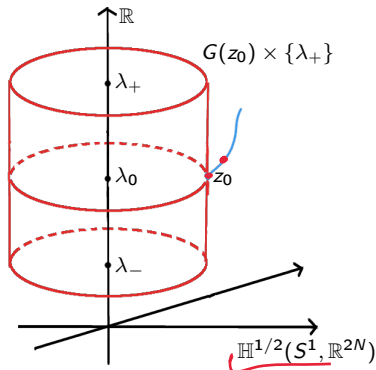
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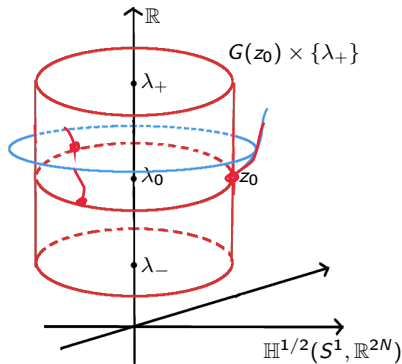
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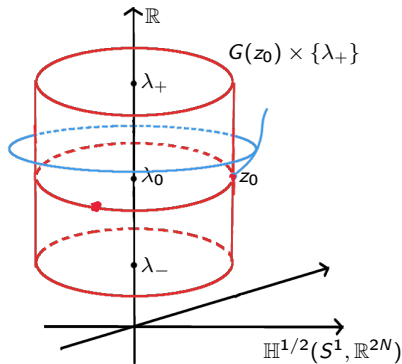
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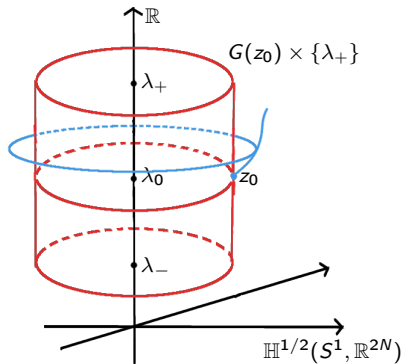
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$$\nabla_G - \deg(\nabla \Phi, \mathcal{O}) = \Upsilon_G(\mathcal{CJ}_G(\mathcal{O}, -\nabla \Phi)).$$



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GS - G -homotopy types of G -spectra

$U(G)$ - Euler ring of a compact Lie group G

$\mathcal{CJ}_G \in GS$ (Izydorek, 2002)
 for compact pert. of linear

$\Upsilon_G : GS \rightarrow U(G)$
 (Gołębiewska i Rybicki, 2013)

Bifurcation problem

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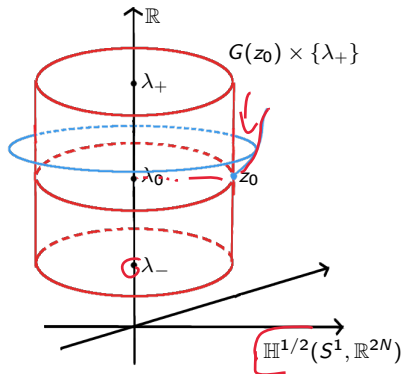
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$$\Upsilon_G(\mathcal{CJ}_G(G(z_0), -\nabla \Phi(\cdot, \lambda_+))) \neq \Upsilon_G(\mathcal{CJ}_G(G(z_0), -\nabla \Phi(\cdot, \lambda_-))).$$

The end of a proof

- We prove the bifurcation of solutions of $\nabla_z \Phi(z, \lambda) = 0$ on the function space $\mathbb{H}^{1/2}(S^1, \mathbb{R}^{2N})$ from any point of the orbit $G(z_0) \times \{\lambda_0\}$.
- These solutions solve the original problem $\dot{z}(t) = J\nabla H(z(t))$ with periods close to $2\pi\lambda_0$.
- The period $2\pi\lambda_0$ is minimal since there is no bifurcation on the level λ_0/k for any $k \in \mathbb{N}$.

$$\frac{2\pi\lambda_0}{3}$$

Let $z(t) \times \{\lambda\}$ be a solution close to $z_0 \times \{\lambda_0\}$ in $\mathbb{H}^{1/2}(S^1, \mathbb{R}^{2N}) \times \mathbb{R}$.
 The map $z(t) \rightarrow \nabla H(z(t))$ is continuous from $L^2(S^1, \mathbb{R}^{2N})$ to $L^2(S^1, \mathbb{R}^{2N})$.

Let $\varepsilon > 0$ and we choose $0 < \delta < \varepsilon$, such that

$\|z - z_0\|_{L^2(S^1, \mathbb{R}^{2N})} \leq \|z - z_0\|_{\mathbb{H}^{1/2}(S^1, \mathbb{R}^{2N})} < \delta$ implies

$$\|\nabla H(z)\|_{L^2(S^1, \mathbb{R}^{2N})} = \|\nabla H(z) - \nabla H(z_0)\|_{L^2(S^1, \mathbb{R}^{2N})} < \varepsilon.$$

Then

$$\begin{aligned} \|z - z_0\|_{L^\infty(S^1, \mathbb{R}^{2N})}^2 &\leq c \|z - z_0\|_{\mathbb{H}^1(S^1, \mathbb{R}^{2N})}^2 = \\ &= c \left(\|z - z_0\|_{L^2(S^1, \mathbb{R}^{2N})}^2 + \|(z - z_0)'\|_{L^2(S^1, \mathbb{R}^{2N})}^2 \right) = \\ &= c \left(\|z - z_0\|_{L^2(S^1, \mathbb{R}^{2N})}^2 + \|\lambda J \nabla H(z)\|_{L^2(S^1, \mathbb{R}^{2N})}^2 \right) \leq \\ &\leq c(1 + (\lambda_0 + \theta)^2) \varepsilon^2. \end{aligned}$$

Let $z(t) \times \{\lambda\}$ be a solution close to $z_0 \times \{\lambda_0\}$ in $\mathbb{H}^{1/2}(S^1, \mathbb{R}^{2N}) \times \mathbb{R}$.

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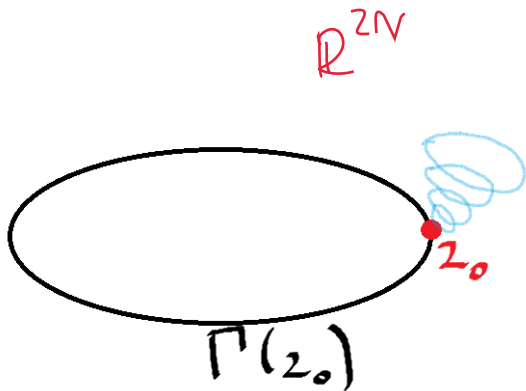
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Plan

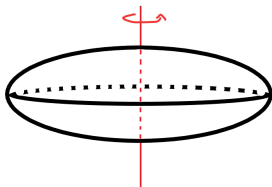
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Quasi-periodic motions close to geostationary orbit

We study motions near the geostationary orbit of an oblate spheroid.

$$U_G(r, \theta) = -G \frac{E}{r} \left(1 - \sum_{n=2}^{\infty} \left(\frac{R}{r} \right)^n J_n P_n(\cos \theta) \right),$$

E - mass, R - equatorial radius, P_n - n -th Legendre polynomial, J_n - coefficients ($J_2 = 1.0826359 \cdot 10^{-3}$ for the Earth).



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Approximation:

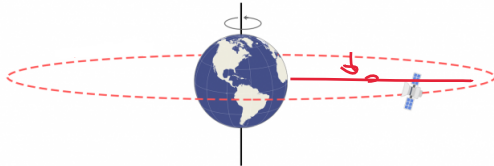
$$U(r, \theta) = -\frac{GE}{r} \left(1 - \frac{J_2 R^2}{r^2} P_2(\cos \theta) \right).$$

By the change of coordinates ($c = \frac{1}{2} R^2 J_2 > 0$, $d = \sqrt{r^2 + z^2}$):

$$V(r, z) = -\frac{1}{d} \left(1 - \frac{c}{d^2} \left(3 \frac{z^2}{d^2} - 1 \right) \right) = -\frac{1}{d} - \frac{c}{d^3} + \frac{3cz^2}{d^5},$$

Fact

Any oblate spheroid possesses exactly one geostationary orbit in a plane perpendicular to rotation axis.



<https://www.everythingrf.com/community/what-is-a-geostationary-orbit>

ω - angular velocity of a particle on geostationary orbit

Hamiltonian reformulation

$$\mathcal{H}(q_1, q_2, q_3, p_1, p_2, p_3) = \frac{1}{2}(p_1^2 + p_2^2 + p_3^2) + \omega(q_1 p_2 - q_2 p_1) - \frac{1}{d} - \frac{c}{d^3} + \frac{3cq_3^2}{d^5},$$

where $c = \frac{1}{2}R^2 J_2 > 0$, $d = \sqrt{q_1^2 + q_2^2 + q_3^2}$, $z_0 = (d_0, 0, 0, 0, -\omega d_0, 0)$.

- (A1) $H: \mathbb{R}^{2N} \rightarrow \mathbb{R}$ is a Γ -invariant Hamiltonian of the class C^2 ,
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$N=3$

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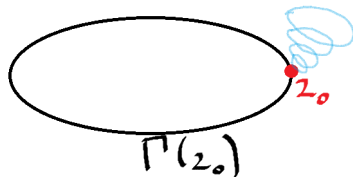
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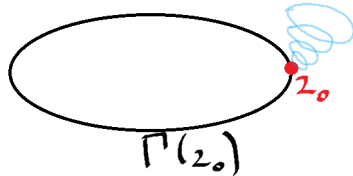
$SO(2)$

$$\left[m^+(\nabla^2 \mathcal{H}(z_0)) = \underline{4}, m^-(\nabla^2 \mathcal{H}(z_0)) = 1, \dim \ker \nabla^2 \mathcal{H}(z_0) = 1 \right]$$

There exist a family of periodic solutions with trajectories arbitrarily close to z_0 (in the rotating frame!)



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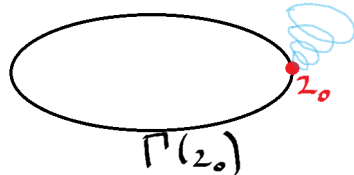
geostationary satellite



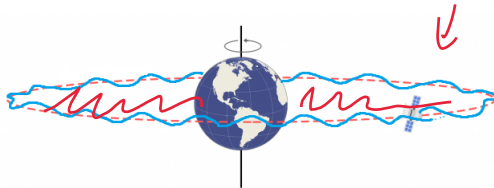
quasi-periodic satellite



There exist a family of periodic solutions with trajectories arbitrarily close to z_0 (in the rotating frame!)



In the original problem there are quasi-periodic, solutions with trajectories arbitrarily close to geostationary orbit.



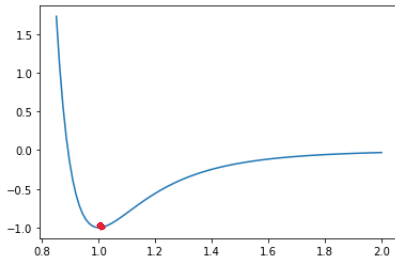
.

Lennard-Jones N -body problem

$$\ddot{q}(t) = -\nabla U(q(t))$$

$$U(q) = \sum_{1 \leq i < j \leq N} \left(\frac{1}{|q_i - q_j|^{12}} - \frac{2}{|q_i - q_j|^6} \right),$$

where $q = (q_1, q_2, \dots, q_N) \in (\mathbb{R}^2)^N$ and $q_i \in \mathbb{R}^2$ is a position of the i -th particle.



$$\frac{1}{r^{12}} - \frac{2}{r^6}$$

$$N = 2 \text{ i } N = 3$$

$$U(q_1, q_2) = \frac{1}{|q_1 - q_2|^{12}} - \frac{2}{|q_1 - q_2|^6}$$

M. Corbera, J. Llibre, and E. Pérez-Chavela. Equilibrium points and central configurations for the Lennard-Jones 2- and 3-body problems. *Celestial Mech. Dynam. Astronom.*, 89(3):235–266, 2004.

- families of equilibria
- relative equilibria

Periodic solutions

- $N = 2$: the existence of non-stationary periodic solutions emanating from equilibrium $(0, \frac{1}{2}, 0, -\frac{1}{2})$ with minimal periods close $\pi/6$.
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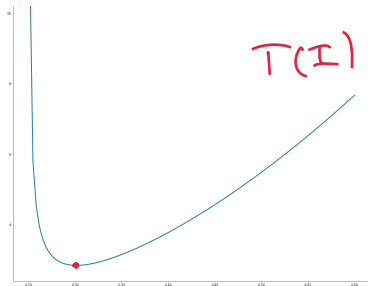
Quasi-periodic solutions, $N = 2$

Twierdzenie, Corbera, Llibre, Pérez-Chavela, 2004

For any $I \in (\frac{1}{4}, \infty)$ the set

$$CC = \{(q_1, q_2) \in \mathbb{R}^2 \times \mathbb{R}^2 : q_2 = -q_1, |q_1 - q_2| = 2\sqrt{I}\}$$

is a family of central configurations generating periodic solutions with period $T(I)$.



Quasi-periodic solutions, $N = 2$

Rotating frame $\rightarrow SO(2)$ -equivariant Hamiltonian system with equilibria.

Theorem

For $I \in (\frac{1}{4}, \frac{1}{4} \sqrt[3]{\frac{5}{2}}) \setminus \{\frac{1}{4} \sqrt[3]{\frac{7}{4}}\}$ there exists a family of quasi-periodic solutions of the Lennard-Jones 2-body problem emanating from relative equilibrium.

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D. Strzelecki.

Periodic solutions of symmetric Hamiltonian systems.

Arch. Rational Mech. Anal., 237:921–950, 2020.



D. Strzelecki.

Bifurcations of quasi-periodic solutions from relative equilibria in the Lennard-Jones 2-body problem.

Celestial Mech. Dynam. Astronom., art. 44, 2021.

Thank you for your attention!

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$$\Gamma_{x_1} = \mathbb{Z}_2 \Rightarrow S^1(x_1) \approx_{S^1} S^1 / \mathbb{Z}_2$$


x_1



$$\Gamma_{x_2} = \mathbb{Z}_3 \Rightarrow S^1(x_2) \approx_{S^1} S^1 / \mathbb{Z}_3$$


x_2




$$\Gamma_{x_1} = \mathbb{Z}_2 \Rightarrow S^1(x_1) \approx_{S^1} S^1 / \mathbb{Z}_2$$


A diagram showing a point x_1 on a circle, with a red oval highlighting the circle.

$$\chi_{S^1}(S^1 / \mathbb{Z}_2^+) \neq \chi_{S^1}(S^1 / \mathbb{Z}_3^+) \in U(S^1)$$


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A diagram showing a point x_2 on a circle, with a red oval highlighting the circle.

$$\Gamma_{x_1} = \mathbb{Z}_2 \Rightarrow S^1(x_1) \approx_{S^1} S^1/\mathbb{Z}_2$$


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Julian I. Palmore

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Uwaga 1

Dla zwartej grupy Liego G oraz gładkiej rozmaitości M , jeżeli działanie grupy G jest **wolne**, to przestrzeń orbit M/G jest gładką rozmaitością.

Uwaga 2

Jeżeli działanie zwartej grupy Liego nie jest wolne, to spójne składowe przestrzeni orbit M/G tworzą stratyfikację Whitney'a.

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