When escape trajectories become singular periodic orbits

## GDM Seminar

# Eva Miranda (joint work with Cédric Oms and Daniel Peralta-Salas)

## UPC-BGSMath & Observatoire de Paris

## Restricted planar circular 3-body problem

Simplified version of the general 3-body problem:

• One of the bodies has negligible mass.

The other two bodies move in circles following Kepler's laws for the 2-body problem.

The motion of the small body is in the same plane.



## Restricted planar circular 3-body problem

• Time-dependent potential:  $U(q,t) = \frac{1-\mu}{|q-q_E(t)|} + \frac{\mu}{|q-q_M(t)|}$ Time-dependent Hamiltonian:  $H(q,p,t) = \frac{|p|^2}{2} - U(q,t), \quad (q,p) \in \mathbf{R}^2 \setminus \{q_E,q_M\} \times \mathbb{R}^2$ Rotating coordinates  $\rightsquigarrow$  Time independent Hamiltonian  $H(q,p) = \frac{p^2}{2} - \frac{1-\mu}{|q-q_E|} + \frac{\mu}{|q-q_M|} + p_1q_2 - p_2q_1$ 



*H* has 5 critical points:  $L_i$  Lagrange points  $(H(L_1) \le \cdots \le H(L_5))$ Periodic orbits of  $X_H$ ? Perturbative methods (dynamical systems) or.... contact geometry!

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•  $\Sigma \subset (W, \omega)$  be a hypersurface.

X Liouville vector field  $(\mathcal{L}_X \omega = \omega) \pitchfork \Sigma \rightsquigarrow (\Sigma, \alpha = \iota_X \omega)$  is contact. If  $\Sigma = H^{-1}(c)$ , then  $R_{\alpha} \cong X_H|_{H=c}$ .

### Weinstein conjecture

Let  $(M, \alpha)$  closed contact manifold. Then  $R_{\alpha}$  admits periodic orbits.

• For  $c < H(L_1)$ ,  $\Sigma_c = H^{-1}(c)$  has 3 connected components:  $\Sigma_c^E$  (the satellite stays close to the earth),  $\Sigma_c^M$  (to the moon), or it is far away.

### Albers–Frauenfelder–Koert–Paternain

For 
$$c < H(L_1)$$
,  $X = (q - q_E) \frac{\partial}{\partial q}$  is transverse to  $\Sigma_c^E$ .

## $\rightsquigarrow (\Sigma_c^E, \iota_X \omega)$ is contact.

But Weinstein conjecture does not apply because of non-compactness (collision!)

**:** :

## Moser regularization of the restricted 3-body problem

• Via Moser's regularization  $\Sigma_c^E$  can be compactified to  $\overline{\Sigma}_c^E \cong \mathbf{R}P(3)$ . The Liouville vector field  $X = (q - q_E)\frac{\partial}{\partial q}$  extends to the regularization.

Hence  $\overline{\Sigma}_{c}^{E}$  is contact.

### Theorem (Albers–Frauenfelder–Koert–Paternain)

For any value  $c < H(L_1)$ , the regularized RPC3BP admits at least one closed orbit with energy c.



 Where are those periodic orbits? Maybe on the collision set? Keep track of the singularities in the geometric structure? ...b<sup>m</sup>-symplectic and b<sup>m</sup>-contact geometry!

## Euler Flows and contact structures

• Euler equations model the dynamics of an **inviscid and incompressible fluid flow**.

$$\begin{cases} \frac{\partial X}{\partial t} + (X \cdot \nabla)X = -\nabla P\\ \operatorname{div} X = 0 \end{cases}$$



Beltrami fields:  $\operatorname{curl} u = fu$  div u = 0.  $\rightsquigarrow$  stationary solutions with constant Bernoulli function  $B = P + \frac{1}{2}g(u, u)$ .

In terms of  $\alpha = \iota_X g$ ,  $\mu$  volume form stationary Euler equations read

$$\begin{cases} \iota_X d\alpha = -dB\\ d\iota_X \mu = 0 \end{cases}$$

## The contact-Beltrami correspondence

Main trick: If X is non-vanishing rotational Beltrami then  $\alpha = \iota_X g$  is contact.

• The Beltrami equation  $\iff d\alpha = f\iota_X\mu$ . Since f > 0 and X does not vanish  $\Rightarrow \alpha \wedge d\alpha = f\alpha \wedge \iota_X\mu > 0$ .

X satisfies  $\iota_X(d\alpha) = \iota_X \iota_X \mu = 0$  so  $X \in \ker d\alpha \iff$  it is a reparametrization of the Reeb vector field by the function  $\alpha(X) = g(X, X)$ .



Etnyre-Ghrist: Beltrami fields ++++ contact structures.

With Cardona and Peralta-Salas we have extended this picture to manifolds with cylindrical ends to get singular contact structures.

## The Symplectic/Contact mirror



Symplectic	Contact
$\dim M = 2n$	$\dim M = 2n + 1$
2-form $\omega$ , non-degenerate $d\omega=0$	1-form $lpha$ , $lpha \wedge (dlpha)^n  eq 0$
Hamiltonian $\iota_{X_H}\omega=-dH$	Reeb $lpha(R)=1$ , $\iota_R dlpha=0$
	$Ham. \ \begin{cases} \iota_{X_H} \alpha = H \\ \iota_{X_H} d\alpha = -dH + R(H) \alpha. \end{cases}$

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## The Symplectic/Contact mirror "reloaded"

<b>Symplectic</b>	Contact
$\dim M = 2n$	$\dim M = 2n + 1$
2-form $\omega$ , non-degenerate $d\omega = 0$	1-form $\alpha$ , $\alpha \wedge (d\alpha)^n \neq 0$
Hamiltonian $\iota_{X_H}\omega = -dH$	Reeb $\alpha(R) = 1$ , $\iota_R d\alpha = 0$
	${\rm Ham.}  \begin{cases} \iota_{X_H} \alpha = H \\ \iota_{X_H} d\alpha = -dH + R(H) \alpha. \end{cases}$

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## Singular forms

A vector field v is a b-vector field if v<sub>p</sub> ∈ T<sub>p</sub>Z for all p ∈ Z. The b-tangent bundle <sup>b</sup>TM is defined by

$$\Gamma(U, {}^{b}TM) = \left\{ \begin{array}{c} \text{b-vector fields} \\ \text{on } (U, U \cap Z) \end{array} \right\}$$



• The *b*-cotangent bundle  ${}^{b}T^{*}M$  is  $({}^{b}TM)^{*}$ . Sections of  $\Lambda^{p}({}^{b}T^{*}M)$  are *b*-forms,  ${}^{b}\Omega^{p}(M)$ . The standard differential extends to

 $d: {}^{b}\Omega^{p}(M) \to {}^{b}\Omega^{p+1}(M)$ 

A *b*-symplectic form is a closed, nondegenerate, *b*-form of degree 2. This dual point of view, allows to prove a *b*-Darboux theorem and semilocal forms via an adaptation of Moser's path method because we can play the same tricks as in the symplectic case.

We can introduce *b*-contact structures on a manifold  $M^{2n+1}$  as *b*-forms of degree 1 for which  $\alpha \wedge (d\alpha)^n \neq 0$ .

The *b*-tangent bundle can be replaced by other algebroids (E-symplectic) known to Nest and Tsygan.



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### Theorem (Guillemin-M.-Weitsman)

Given a  $b^m$ -symplectic structure  $\omega$  on a compact manifold  $(M^{2n}, Z)$ :

• If m = 2k, there exists a family of symplectic forms  $\omega_{\epsilon}$  which coincide with the  $b^m$ -symplectic form  $\omega$  outside an  $\epsilon$ -neighbourhood of Z and for which the family of bivector fields  $(\omega_{\epsilon})^{-1}$  converges in the  $C^{2k-1}$ -topology to the Poisson structure  $\omega^{-1}$  as  $\epsilon \to 0$ .

If m = 2k + 1, there exists a family of folded symplectic forms  $\omega_{\epsilon}$  which coincide with the  $b^m$ -symplectic form  $\omega$  outside an  $\epsilon$ -neighbourhood of Z.

In particular:

• Any  $b^{2k}$ -symplectic manifold admits a symplectic structure.

Any  $b^{2k+1}$ -symplectic manifold admits a folded symplectic structure.

The converse is not true:  $S^4$  admits a folded symplectic structure but no *b*-symplectic structure.

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## Deblogging everything...



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All 3-dimensional manifolds are contact (Martinet-Lutz) in higher dimensions generalized by Casals-Presas-Pancholi in dimension 5 and more generally

### Theorem (Borman-Eliashberg-Murphy)

Any almost contact closed manifold is contact.



## Theorem (Even singularization, M-Oms)

For any pair (M, Z) of contact manifold and convex hypersurface there exists a  $b^{2k}$ -contact structure for all k having Z as critical set.

### Corollary (of Giroux theorem)

For any 3-dimensional manifold and any generic surface Z, there exists a  $b^{2k}$ -contact structure on M realizing Z as the critical set.

## What about periodic orbits?



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## Contact geometry of RPC3BP revisited

In rotating coordinates:  $H(q,p) = \frac{|p|^2}{2} - \frac{1-\mu}{|q-q_E|} + \frac{\mu}{|q-q_M|} + p_1q_2 - p_2q_1$ 

#### Lemma

The vector field  $Y = p \frac{\partial}{\partial p}$  is a Liouville vector field and is transverse to  $\Sigma_c$  for c > 0.

- Symplectic polar coordinates:  $(r, \alpha, P_r, P_\alpha)$ . McGehee change of coordinates:  $r = \frac{2}{x^2}$ .
- $b^3$ -symplectic form:  $-4\frac{dx}{x^3} \wedge dP_r + d\alpha \wedge dP_{\alpha}$ .

### Singular contact

Is  $\Sigma_c b^3$ -contact after McGehee? Can we apply the results on periodic orbits?

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After the McGehee change, the Liouville vector field  $Y = p \frac{\partial}{\partial p}$  is a  $b^3$ -vector field that is everywhere transverse to  $\Sigma_c$  for c > 0 and the level-sets  $(\Sigma_c, \iota_Y \omega)$  for c > 0 are  $b^3$ -contact manifolds.

The critical set is a cylinder.

The Reeb vector field admits infinitely many non-trivial periodic orbits on the critical set. <a></a>

#### Proof.

On the critical set, Hamiltonian  $H = \frac{1}{2}P_r^2 - P_\alpha$ , so that  $Y(H) = P_r^2 - P_\alpha = \frac{1}{2}\frac{P_r^2}{2} + c > 0;$ 

 $b^{3}\text{-contact form } \alpha = (P_{r}\frac{dx}{x^{3}} + P_{\alpha}d\alpha)|_{H=c} \text{ with } Z = \{(x, \alpha, P_{r}, P_{\alpha})|x = 0, \frac{1}{2}P_{r}^{2} - P_{\alpha} = c\};$ 

 $R_{\alpha}|_{Z} = X_{P_{r}}$  and the cylinder is foliated by periodic orbits.

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- $b^3$ -contact form  $\alpha = (P_r \frac{dx}{x^3} + P_\alpha d\alpha)|_{H=c}$  with  $Z = \{(x, \alpha, P_r, P_\alpha) | x = 0, \frac{1}{2}P_r^2 P_\alpha = c\};$
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$$\begin{split} b^3\text{-contact form } \alpha &= (P_r \frac{dx}{x^3} + P_\alpha d\alpha)|_{H=c} \text{ with } \\ Z &= \{(x, \alpha, P_r, P_\alpha) | x = 0, \frac{1}{2}P_r^2 - P_\alpha = c\}; \end{split}$$

 $R_{\alpha}|_{Z}=X_{P_{r}}$  and the cylinder is foliated by periodic orbits.



The Reeb vector field of a contact compact manifold admits at least one periodic orbit.

• Taubes proved it in dimension 3 for regular contact structures. What about singular contact structures?

## Theorem (M-Oms)

Given a  $b^{2k}$ -contact manifold with convex critical set Z, there exists a family of contact forms  $\alpha_{\epsilon}$  agreeing with a  $b^{2k}$ -contact form  $\alpha$  outside of an  $\epsilon$ -neighbourhood of Z. The family of bi-vector fields  $\Lambda_{\epsilon}$  and the family of vector fields  $\mathbf{R}_{\epsilon}$  associated to the Jacobi structure of the contact form  $\alpha_{\epsilon}$  converges to the bivector field  $\Lambda$  and to the vector field R in the  $C^{2k-1}$ -topology as  $\epsilon \to 0$ .

## Theorem (M-Oms)

Let  $(M, \alpha)$  be a closed  $b^{2k}$ -contact manifold of dimension 3, then there exists a family of periodic orbits  $\mathcal{O}_{\epsilon}$  associated to the Reeb vector fields  $R_{\epsilon}$ .

## Periodic orbits via desingularization

### <u>What one would like to do</u>: Take the limit $\epsilon \to 0$ .

<u>Problem:</u>  $\mathcal{O}_{\epsilon}$  need not be continuous. as it comes from critical point of the action functional

for  $\gamma$  in the loop space  $C^{\infty}(S^1, M)$ .



#### Lemma

If there exist  $\epsilon > 0$ , such that there exists a periodic orbit of  $R_{\alpha_{\epsilon}}$  of type (1), then this is a periodic Reeb orbit of  $(M, \alpha)$ .

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$$\mathcal{A}_{\alpha_{\epsilon}}(\gamma) = \int_{\gamma} \alpha_{\epsilon}$$

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Let  $(M, \alpha)$  be a 3-dimensional  $b^m$ -contact manifold and assume the critical hypersurface Z to be closed. Then there exists infinitely many periodic Reeb orbits on Z.

### Proof.

• The restriction on Z of the 2-form  $\Theta = ud\beta + \beta \wedge du$  is symplectic and the Reeb vector field is Hamiltonian.

$$\alpha = u \frac{dz}{z^m} + \beta$$

- u is non-constant on Z.
- $R_{lpha}$  is Hamiltonian on Z for -u,
- $u^{-1}(p)$  where p regular is a circle,
- $R_{\alpha}$  periodic on  $u^{-1}(p)$ .

## No periodic orbits away from Z

There are compact  $b^m$ -contact manifolds (M, Z) of any dimension for all  $m \in \mathbb{N}$  without periodic Reeb orbits on  $M \setminus Z$ .

### Example

• 
$$S^3 \subset (\mathbf{R}^4, \omega)$$

• 
$$X = \frac{1}{2}x_1\frac{\partial}{\partial x_1} + y_1\frac{\partial}{\partial y_1} + \frac{1}{2}(x_2\frac{\partial}{\partial x_2} + y_2\frac{\partial}{\partial y_2})$$
 Liouville v.f.

• 
$$R_{\alpha} = 2x_1^2 \frac{\partial}{\partial x_1} - x_1y_1 \frac{\partial}{\partial y_1} + 2x_2 \frac{\partial}{\partial y_2} - 2y_2 \frac{\partial}{\partial x_2}$$

• On  $Z = S^2$ : rotation, way from Z, no periodic orbits.

### Example

• 
$$(\mathbb{T}^3, \sin\phi \frac{dx}{\sin x} + \cos\phi dy)$$
.  $R_{\alpha} = \sin\phi \sin x \frac{\partial}{\partial x} + \cos\phi \frac{\partial}{\partial y}$ .

• Z = two disjoint copies of the 2-torus  $\mathbb{T}^2$  and the Reeb flow restricted to it is given by  $\cos \phi \frac{\partial}{\partial y}$ .

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## Definition

 $(M^3,\xi=\ker\alpha)$  is overtwisted if there exists  $D^2$  s.t.  $TD\cap\xi$  defines a 1-dimensional foliation given by



A contact manifold that is not overtwisted is called *tight*.

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## Theorem (Hofer '93)

Let  $(M^3,\alpha)$  a closed OT contact manifold. Then there exists a periodic orbit.

Not true for open OT manifolds!

### Definition

A  $b^m$ -contact manifold is overtwisted if there exists an overtwisted disk away from the critical hypersurface Z.

### Definition

A  $b^m$ -contact form  $\alpha$  is  $\mathbb{R}^+$ -invariant around the critical set if  $\alpha = udz + \beta$ , where  $u \in C^{\infty}(Z)$  and  $\beta \in \Omega^1(Z)$ 

Let  $(M^3, \alpha)$  be a closed  $b^m$ -contact manifold with critical set Z. Assume there exists an overtwisted disk in  $M \setminus Z$  and assume that  $\alpha$  is  $\mathbf{R}^+$ -invariant in a tubular neighbourhood around Z. Then there exists

- $igodoldsymbol{\circ}$  a periodic Reeb orbit in  $M\setminus Z$  or
  - a family of periodic Reeb orbits approaching the critical set Z.

Furthermore, the periodic orbits are contractible loops in the symplectization.

The proof is an adaptation of Hofer's techniques.

## An image is worth more than a thousand words...



Figure 5.3: Bishop family blowing-up in the  $\mathbb{R}^+$ -invariant part



Let  $(M^3, \alpha)$  be a  $\mathbb{R}^+$ -invariant contact manifold that is OT away from the  $\mathbb{R}^+$ -invariant part. Then there exists a 1-parametric family of periodic Reeb orbits in the  $\mathbb{R}^+$ -invariant part of M or a periodic Reeb orbit away from the  $\mathbb{R}^+$ -invariant part.

### Mantra

Non-compactness  $+ \mathbf{R}^+$ -invariance = compactness

Question: Applications of this theorem?

## The singular Weinstein conjecture re-loaded

A true singular Weinstein structures should also admit singular orbits as below:



Or.



### Singular Weinstein conjecture

Let  $(M, \alpha)$  be a compact *b*-contact manifold with critical hypersurface Z. Then there exists always a Reeb orbit  $\gamma : \mathbb{R} \to M \setminus Z$  such that  $\lim_{t \to \pm \infty} \gamma(t) = p_{\pm} \in Z$  and  $R_{\alpha}(p_{\pm}) = 0$  (singular periodic orbit).

## We need inspiration...



## True inspiration comes in a hat...



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Singular periodic orbits are a particular case of escape orbits  $\gamma$ ,  $\gamma \subset M \setminus Z$  such that  $\lim_{t\to\infty} \gamma(t) = p$  where p is an equilibrium point in Z (respectively  $\lim_{t\to-\infty} \gamma(t) = p$ ).



Figure: Singular periodic orbit vs. Escape orbits (in green)

*b*-Beltrami vector field  $X \operatorname{curl} X = \lambda X$ 

### Theorem (Cardona-M.-Peralta-Salas)

- Any rotational Beltrami field non-vanishing as a section of  ${}^{b}TM$  on M is a Reeb vector field (up to rescaling) for some *b*-contact form on M.
- Given a *b*-contact form  $\alpha$  with Reeb vector field *X* then any nonzero rescaling of *X* is a rotational Beltrami field for some *b*-metric and *b*-volume form on *M*.

### Practical tip

X is a Beltrami vector field on  $(M,g) \iff$  the Reeb vector field associated to the *b*-contact form  $\alpha = g(X,\cdot)$  is given by  $\frac{1}{\|X\|^2}X$ .

## Escape orbits and Singular orbits

Exact *b*-metric  $\longleftrightarrow$  Melrose *b*-contact forms:

$$g = \frac{dz^2}{z^2} + \pi^* h \tag{1}$$

with h Riemannian metric on Z.

## Theorem (M-Oms-Peralta, "lockdown theorem")

There exists at least  $2 + b_1(Z)$  escape orbits for Reeb vector fields of generic Melrose b-contact forms on (M, Z).



**Proof:** The Beltrami equation  $\rightsquigarrow$  the Hamiltonian function associated to (R, Z) is an eigenfunction of the induced Laplacian on  $Z \rightsquigarrow$  (Uhlenbeck) generically Morse and non-zero critical values.

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## A garden of singular orbits



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## A garden of singular orbits



Figure: Different types of escape and singular periodic orbits:  $\gamma_1$  is a generalized singular periodic orbit,  $\gamma_2, \gamma_3$  are singular periodic orbits

## Generalized singular periodic orbits

### Definition

An orbit  $\gamma : \mathbf{R} \to M \setminus Z$  of a *b*-Beltrami field X is a generalized singular periodic orbit if there exist  $t_1 < t_2 < \cdots < t_k \to \infty$  such that  $\gamma(t_k) \to p_+ \in Z$  and  $t_{-1} > t_{-2} > \cdots > t_{-k} \to -\infty$  such that  $\gamma(t_{-k}) \to p_- \in Z$ , as  $k \to \infty$ .

 $\mathbf{p}_+$  and  $p_-$  may be contained in different components and are not necessarily zeros of X.



This includes oscillatory motions:orbits (q(t), p(t)) in the phase space  $T^*\mathbb{R}^n$  such that  $\limsup_{t\to\pm\infty} \|q(t)\| = \infty$  and  $\liminf_{t\to\pm\infty} \|q(t)\| < \infty$ .

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For 
$$g = \frac{dz^2}{z^2} + dx^2 + dy^2$$
, we can prove more.

### Theorem (M-Oms-Peralta Salas)

When g is semi-locally as above and X a generic asymptotically symmetric b-Beltrami vector field, X has a generalized singular periodic orbit. Moreover, it has a singular periodic orbit or at least 4 escape orbits.

In the case of  $(\mathbb{T}^3, \alpha = C \cos y dx + B \sin x dy + (C \sin y + B \cos x) \frac{dz}{\sin z})$  for  $|B| \neq |C|$ , the singular Weinstein conjecture is satisfied.

- Can we prove existence of singular Weinstein orbits for generic *b*-contact forms?
- Extend the apparatus of variational calculus to extend the action functional to this set-up.

$$\mathcal{A}_{\alpha}(\gamma) = \int_{\gamma} \alpha$$

• Find higher dimensional applications to celestial mechanics (for instance, escape orbits 5-body problem).