

# Polynomial-time equivalent representations of compact sets in Euclidean spaces

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Brattka and Weihrauch [2, Section 4] compared several natural representations of the space  $\mathcal{K}$  of compact subsets of Euclidean space, which induce computability notions that are now well studied and generalized [1, 4]. One of the representations,  $\delta_{\mathcal{K}}^>$ , is based on the fact that compact sets are bounded and closed: a  $\delta_{\mathcal{K}}^>$ -name of  $K \in \mathcal{K}$  consists of a bound on  $K$  (i.e., a finite set of rational balls whose union contains  $K$ ) together with an infinite list enumerating basic sets (rational balls) contained in the complement of  $K$ . Another representation,  $\delta_{\text{cover}}$ , is based on the characterization of compact sets using covers: a  $\delta_{\text{cover}}$ -name of  $K \in \mathcal{K}$  enumerates a set of finitely many basic sets that covers  $K$ . These representations are shown to be computably equivalent.

We discuss possible ways to refine their argument to polynomial-time computability. To make the representations meaningful in the time-bounded context, we need to replace enumeration by recognition: that is, instead of an infinite list of basic sets or covers, we consider a predicate that roughly tells us whether a given set intersects  $K$ , or whether given sets cover  $K$ . This leads to the following representations of  $\mathcal{K}$ :

- A  $\hat{\delta}_{\mathcal{K}}$ -name of  $K \in \mathcal{K}$  is a pair  $(w, D)$  of a bound  $w \in \Sigma^*$  on  $K$  and a predicate  $D \subseteq \Sigma^*$  such that for any rational ball  $B$ , we have  $B \in D$  if  $K$  intersects  $B$ , and  $B \notin D$  if  $K$  does not intersect  $2B$ , the ball with the same centre and twice the radius as  $B$ .
- A  $\hat{\delta}_{\text{cover}}$ -name of  $K \in \mathcal{K}$  is a pair  $(w, C)$  of a bound  $w \in \Sigma^*$  on  $K$  and a predicate  $C \subseteq \Sigma^*$  such that for any finite list  $l = (B_0, \dots, B_{k-1})$  of rational balls, we have  $l \in C$  if  $K \subseteq B_0 \cup \dots \cup B_{k-1}$ , and  $l \notin C$  if  $K \not\subseteq 2B_0 \cup \dots \cup 2B_{k-1}$ .

Note that we are using “soft” recognition: the expected behaviour of the predicates  $C$  and  $D$  is unspecified on some inputs. Computing a  $\hat{\delta}_{\mathcal{K}}$ -name of  $K$  can be thought of as drawing  $K$  on a computer screen with various precision, and was the notion used in the study of complexity of some fractal sets [5, 3]. We show that  $\hat{\delta}_{\mathcal{K}}$  and  $\hat{\delta}_{\text{cover}}$  are polynomial-time equivalent.

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The computable equivalence of  $\delta_{\mathcal{K}}^>$  and  $\delta_{\text{cover}}$  (as well as some other representations) can be generalized to computable metric spaces satisfying the properties called nice closed balls and effective covering [1, Theorem 4.10]. Our argument for polynomial-time equivalence seems to rely on more special properties of Euclidean spaces, and it remains open whether similar generalization is possible.

## References

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