

Symplectic classification of semi-toric integrable systems: recent advances and examples

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Recent advances in Hamiltonian dynamics
and symplectic topology

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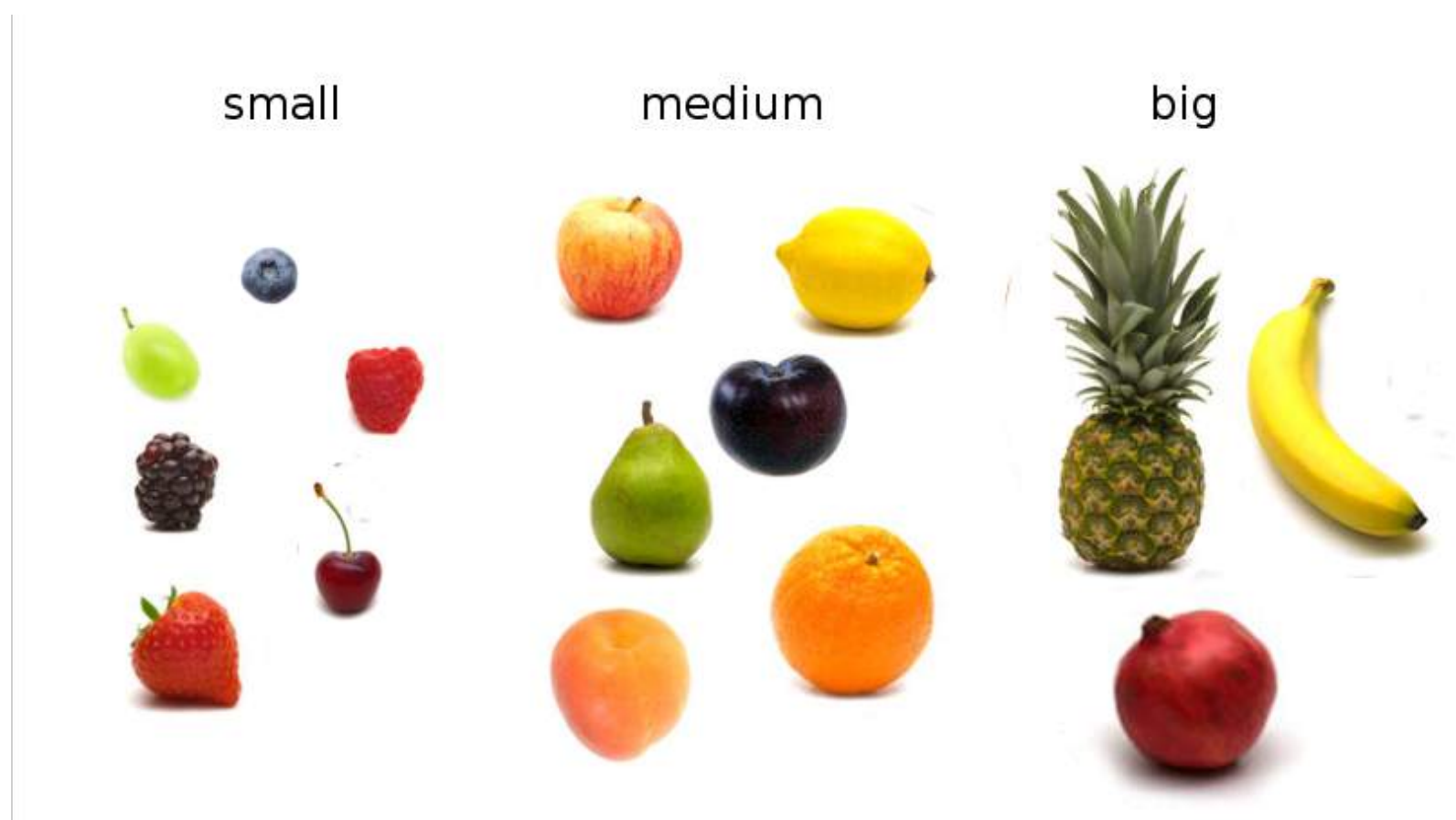
Fundamental
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Classifications

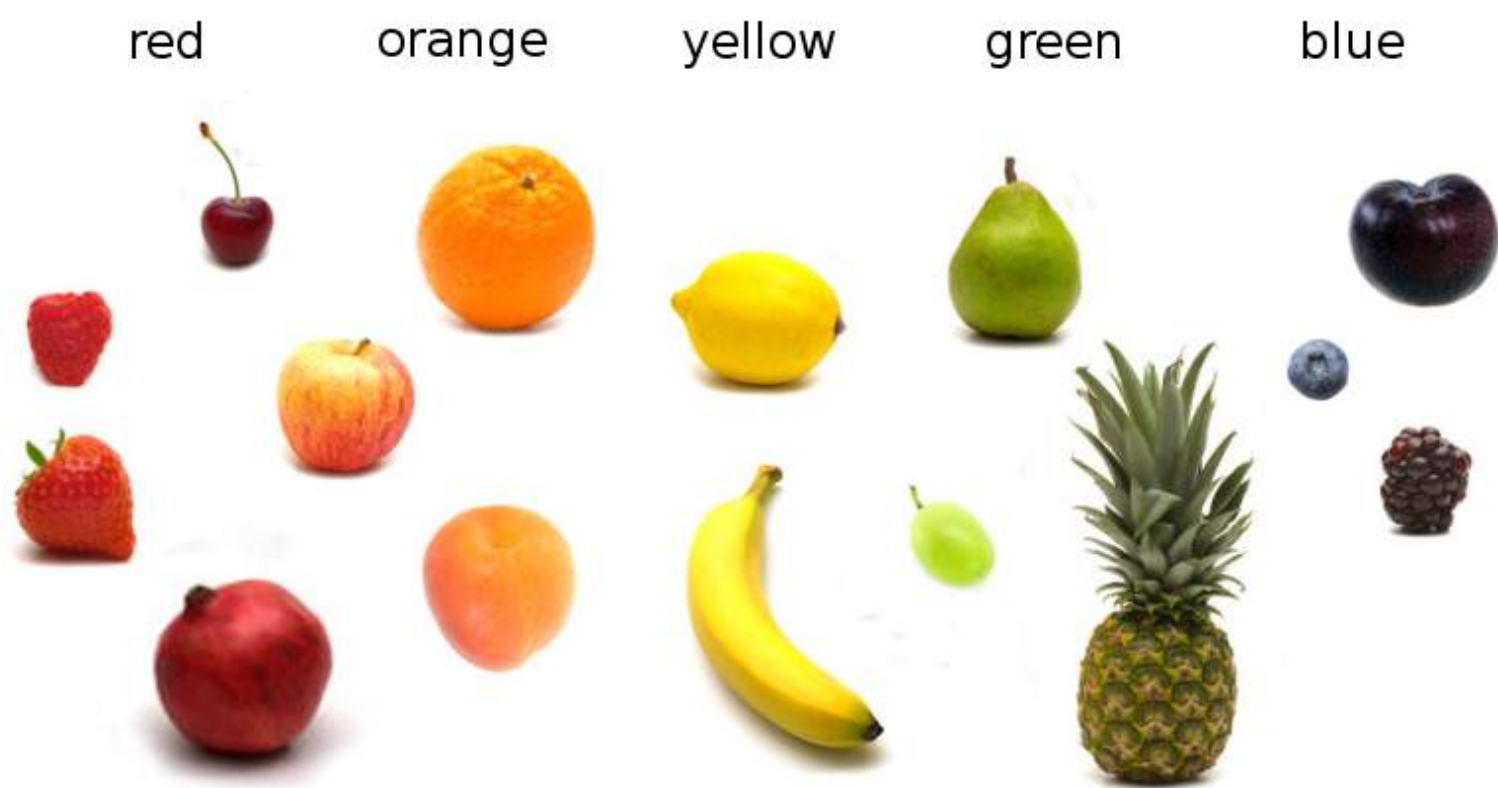
Classifications



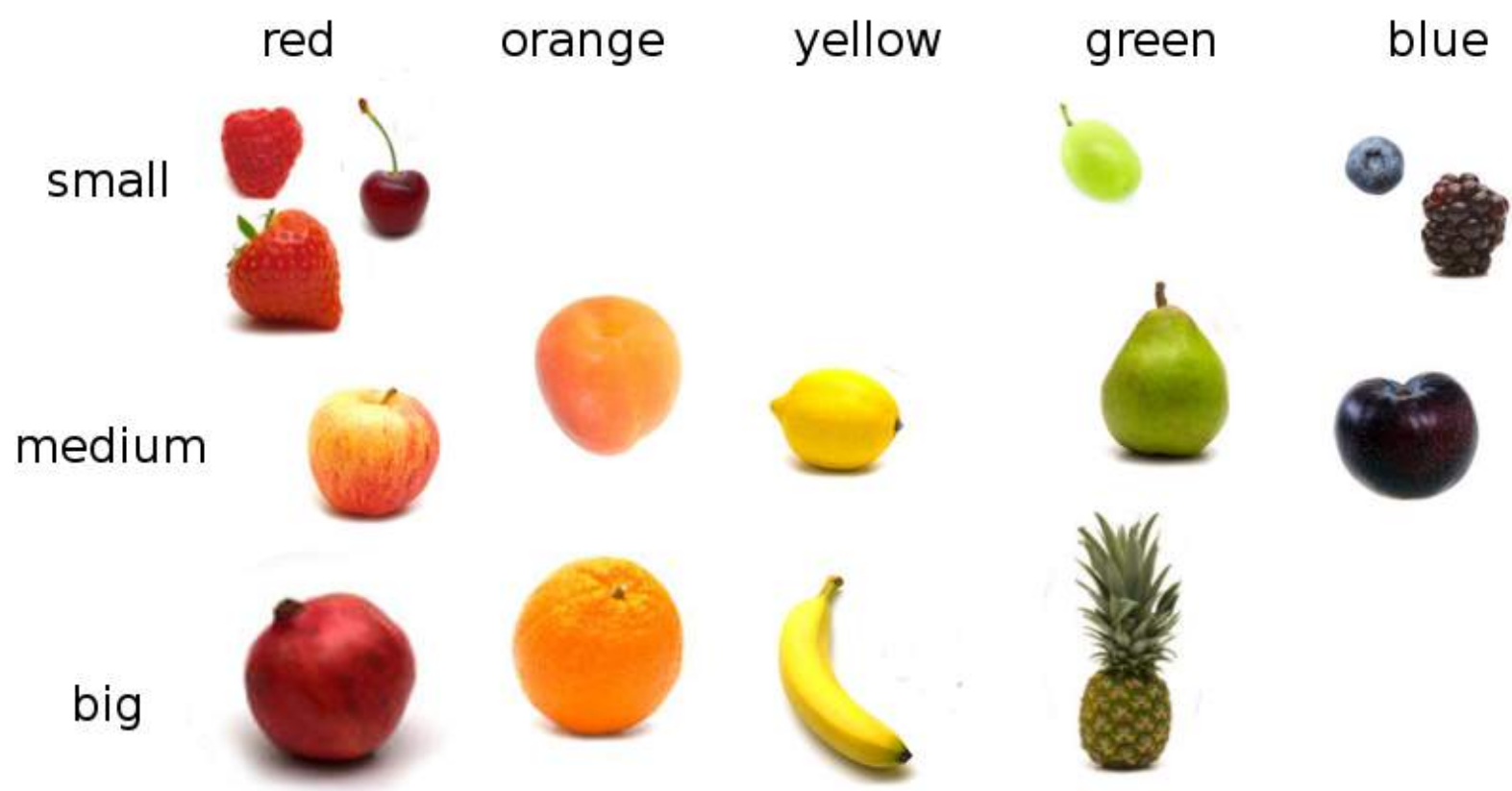
Classifications



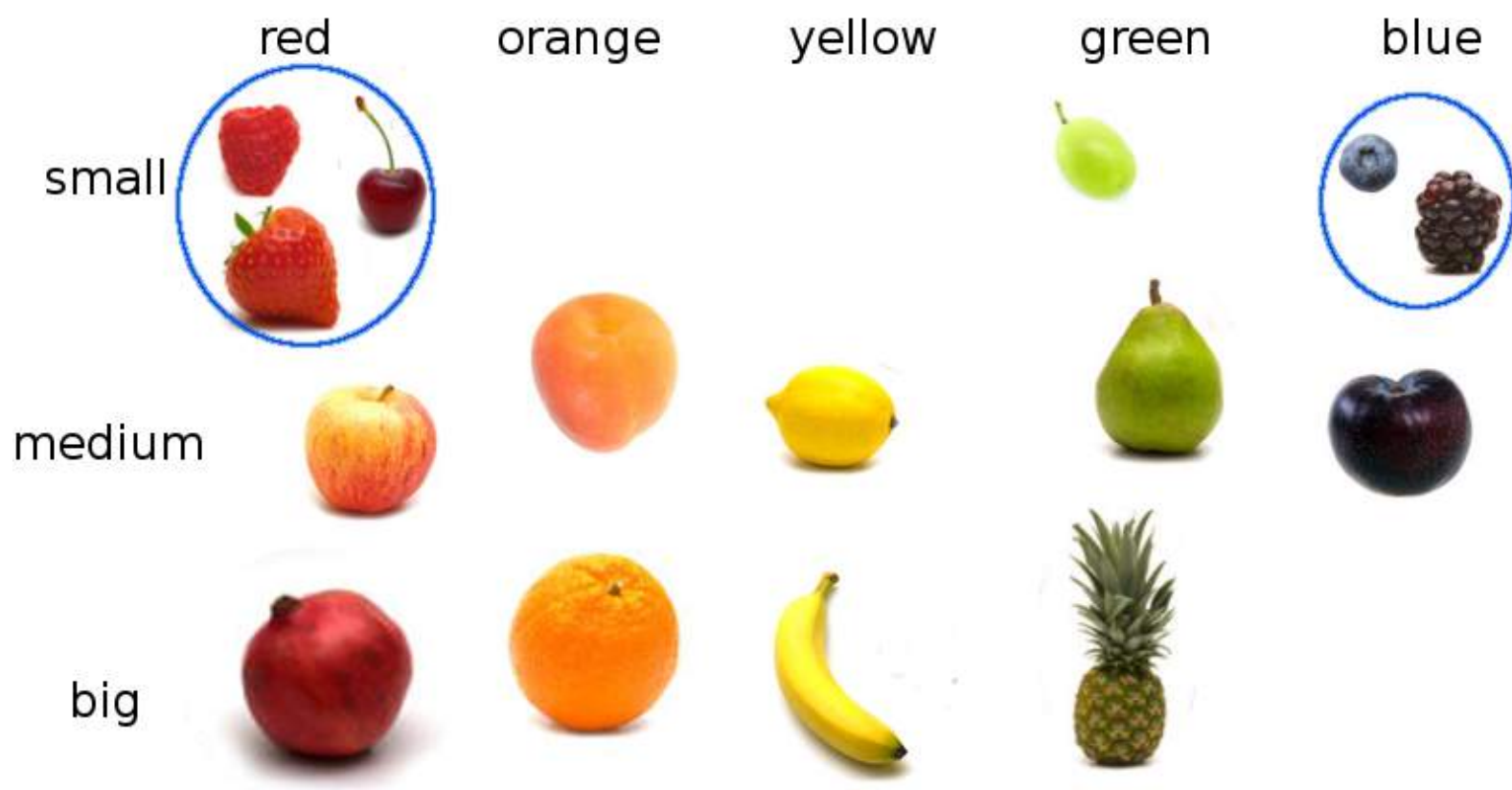
Classifications



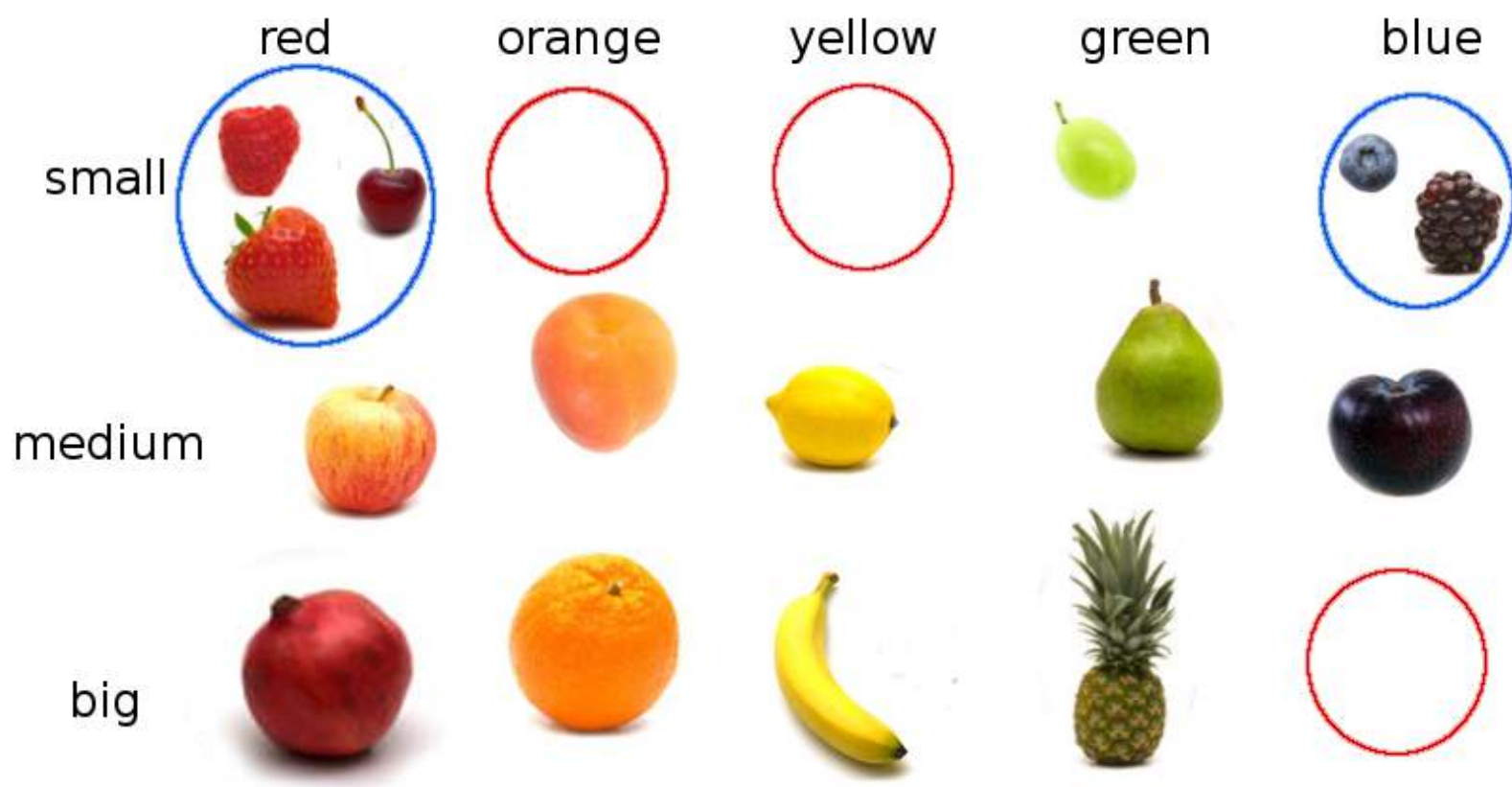
Classifications



Classifications



Classifications



Classifications

Classification:

- ▶ We associate some data to each element of the collection (of topological nature, symplectic nature, diffeomorphic nature...)

Desirable characteristics:

- ▶ Two systems have the same data \leftrightarrow they are **equivalent** (in some sense)
- ▶ Given some **admissible** data, we can construct the corresponding system

Classifications

- ▶ A symplectic classification of all **completely integrable Hamiltonian systems** is desirable but difficult
- ▶ **Toric systems** can be classified using certain polygons (Delzant polytopes)
- ▶ Recently, **semi-toric systems** have been classified in terms of five symplectic invariants by Pelayo and Vũ Ngọc

Completely integrable systems

- ▶ (M, ω) is a $2n$ -dimensional **symplectic manifold**
- ▶ To each smooth function $H : M \rightarrow \mathbb{R}$ (autonomous **Hamiltonian**) we associate a **Hamiltonian vector field** X^H by

$$\omega(X^H, \cdot) = dH(\cdot)$$

and a corresponding **Hamiltonian flow** φ^H

- ▶ The algebra of Hamiltonians $C^\infty(M)$ is endowed with the **Poisson bracket**: $\{J, F\} := \omega(X^J, X^F)$
- ▶ The time-evolution of a function F under the flow of X^H is $\dot{F} = \{H, F\}$
- ▶ If F satisfies $\{H, F\} = 0$, we call it a **constant of motion / first integral**

Completely integrable systems

- ▶ A **completely integrable system** is a Hamiltonian on (M, ω) system where:
 - ▶ $H, F_2, \dots, F_n : M \rightarrow \mathbb{R}$ constants of motion
 - ▶ dH, dF_2, \dots, dF_n linearly independent almost everywhere
 - ▶ $\{F_i, F_j\} = 0$ for $1 \leq i, j \leq n$, where $F_1 := H$
- ▶ The different constants of motion correspond to **continuous symmetries** of the system (Noether's theorem)
- ▶ The **momentum map** $\Phi = (F_1, F_2, \dots, F_n) : M \rightarrow \mathbb{R}^n$. The flows $\varphi^{F_1}, \dots, \varphi^{F_n}$ define an \mathbb{R}^n -action on M that fibrates the manifold

Understanding the **fibration** is key to understand the system:

- ▶ A point $p \in M$ is called **regular** if $D\Phi|_p$ has rank n . Otherwise it is a **critical point**
- ▶ If $\Phi^{-1}(c)$ has only regular points, it is a **regular fibre** and $c \in \mathbb{R}^n$ is a **regular value**
- ▶ If $\Phi^{-1}(c)$ contains critical points, it is a **singular fibre** and $c \in \mathbb{R}^n$ is a **critical value**

Regular and singular fibres

Regular fibres are “boring”:

- ▶ Assume the vector fields X^{F_1}, \dots, X^{F_n} are complete
- ▶ Then each connected component of a regular fibre is diffeomorphic to $\mathbb{R}^{n-k} \times \mathbb{T}^k$. If compact, then \mathbb{T}^n (*Liouville tori*).

Singular fibres might be more “interesting”:

- ▶ If we have n integrals, we will (almost) always have singularities.
- ▶ They correspond to fixed points and relative equilibria subsets, so they describe the dynamics of the system.

Singularities

Local normal form (Eliasson¹, Miranda & Zung²):

Integrable systems are linearisable around (non-degenerate) critical points $p \in M$, i.e. $\exists (x_1, \dots, x_n, \xi_1, \dots, \xi_n)$ local symplectic coordinates and functions q_1, \dots, q_n with $\{q_i, F_j\} = 0 \forall i, j$ where the q_i can be:

- ▶ **Elliptic** component: $q_j = (x_j^2 + \xi_j^2)/2$
- ▶ **Hyperbolic** component: $q_j = x_j \xi_j$
- ▶ **Focus-focus** component: they come in pairs

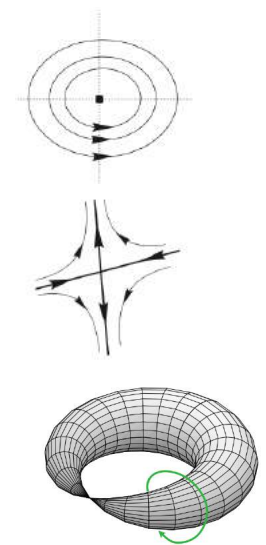
$$\begin{cases} q_{j-1} = x_{j-1} \xi_j - x_j \xi_{j-1} \\ q_j = x_{j-1} \xi_{j-1} + x_j \xi_j \end{cases}$$

- ▶ **Non-singular** component: $q_j = \xi_j$

Moreover, if no hyperbolic components, then the equations $\{F_i, q_j\} = 0$ can be replaced by

$$(\Phi - \Phi(p)) \circ \varphi = g \circ (q_1, \dots, q_n)$$

where $\varphi = (x_1, \dots, x_n, \xi_1, \dots, \xi_n)^{-1}$ and g is a diffeomorphism.



¹ L. Eliasson, Hamiltonian systems with Poisson commuting integrals, PhD Thesis, (1984)

² E. Miranda, N. T. Zung, *A note on equivariant normal forms of Poisson structures*, Math. Res. Lett., (2006)

Semi-toric systems

Singularities

Setting:

- ▶ (M, ω) 4-dimensional connected symplectic manifold
- ▶ $\Phi = (L, H) : M \rightarrow \mathbb{R}^2$ momentum map of a completely integrable system
- ▶ $p \in M$ **critical point**, with $D\Phi|_p < 2$

Definition:

- ▶ p is a **non-degenerate** critical point if the Hessians $D^2L|_p, D^2H|_p$ are linearly independent and if there is a linear combination of them having 4 distinct eigenvalues.

Semi-toric systems

Definition (Pelayo & Vũ Ngọc)³:

A **semi-toric system** is a 4-dimensional completely integrable system $(L, H) : (M, \omega) \rightarrow \mathbb{R}^2$ such that:

- ▶ L is proper
- ▶ L induces an effective Hamiltonian \mathbb{S}^1 -action
- ▶ All singularities are non-degenerate
- ▶ There are no hyperbolic components

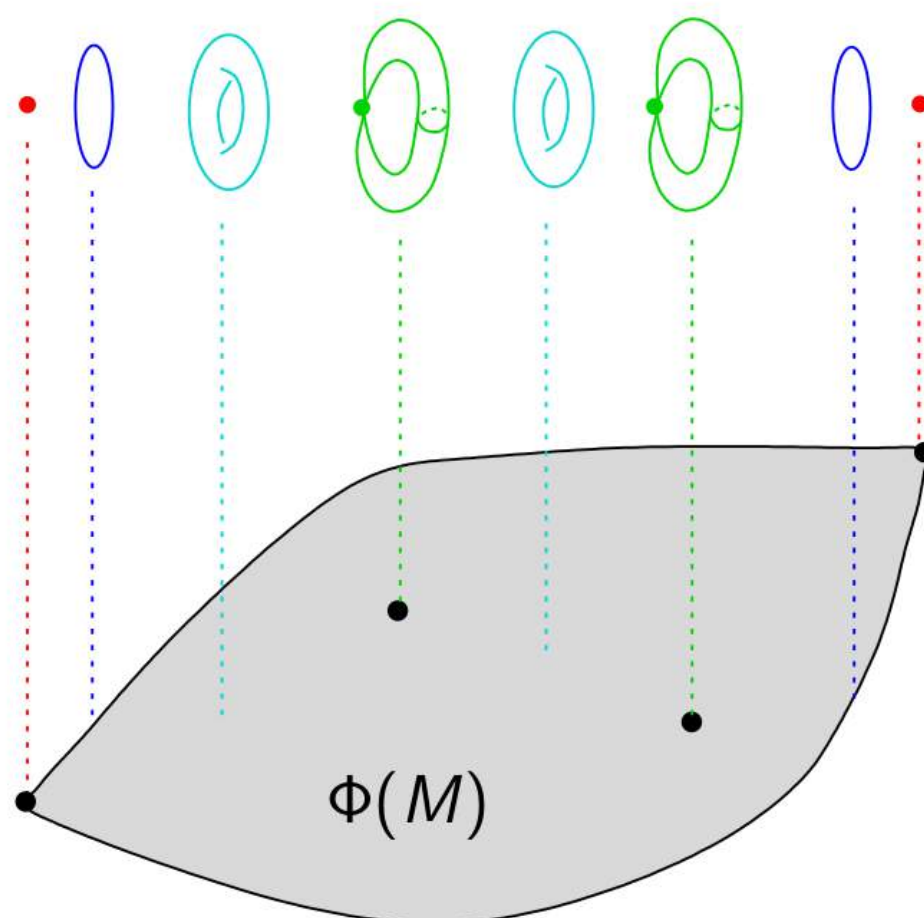
Conclusion: Possible singularities in $\dim=4$:

- ▶ **focus-focus** (rank=0)
- ▶ **elliptic-elliptic** (rank=0)
- ▶ **elliptic-regular** (rank=1)

³ Á. Pelayo, S. Vũ Ngọc, *Semitoric integrable systems on symplectic 4-manifolds*, Invent. Math., (2009)

Singularities

$$\begin{array}{ccc}
 (M, \omega) \supset \Phi^{-1}(z) & & \\
 \downarrow \begin{array}{c} \Phi \\ \parallel \\ (J, H) \end{array} & & \\
 \mathbb{R}^2 \supset \Phi(M) \ni z & &
 \end{array}$$



Example: the coupled spin-oscillator

Coupled spin-oscillator

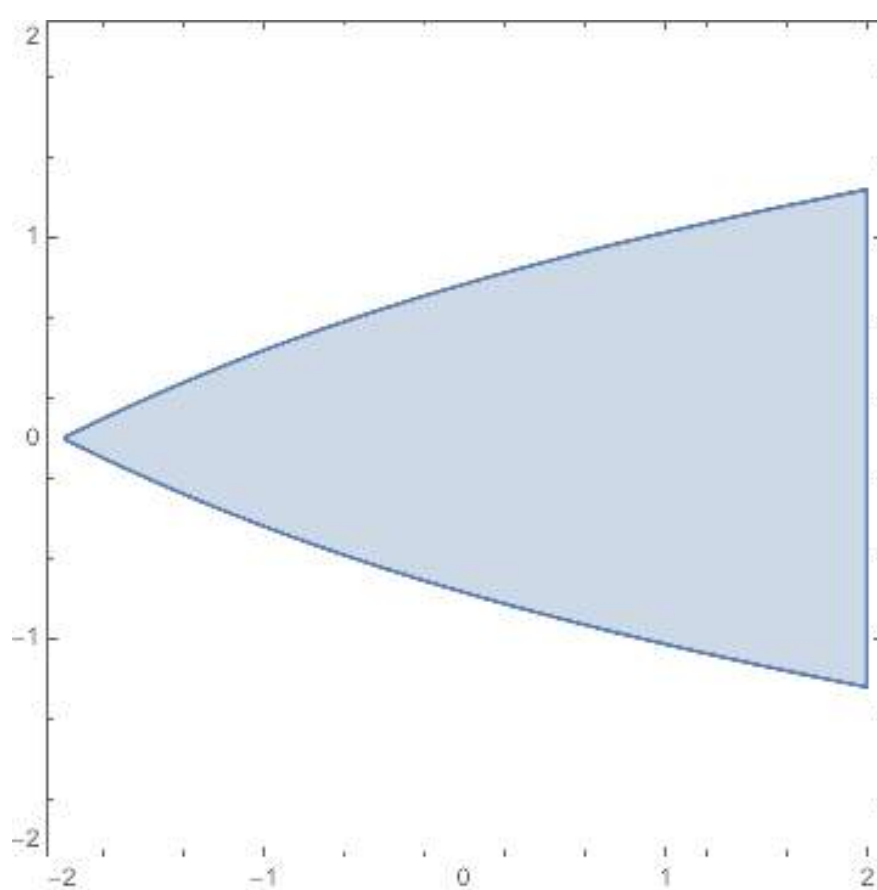
- ▶ The **coupled spin-oscillator** is a 4-dimensional integrable Hamiltonian system with 2 degrees of freedom
- ▶ It consists of the "coupling" of a **classical spin** on \mathbb{S}^2 and a **classical harmonic oscillator** on \mathbb{R}^2
- ▶ It appears in quantum mechanics (cold atoms in non-equilibrium / Jaynes-Cummings model) and there are also classical and semi-classical studies⁴
- ▶ Let $\lambda, \mu > 0$ be positive constants. Let $(x, y, z) \in \mathbb{S}^2$ and $(u, v) \in \mathbb{R}^2$ be coordinates of the space $\mathbb{S}^2 \times \mathbb{R}^2$. Then we define

$$L := \mu \frac{u^2 + v^2}{2} + \lambda(z - 1) \quad H := \frac{1}{2}(ux + vy)$$

⁴ O. Babelon, L. Cantini, B. Douçot, *A semi-classical study of the Jaynes-Cummings model*, J. Stat. Mech. Theory Exp., (2009)

Coupled spin-oscillator

L induces an \mathbb{S}^1 -action. None of the functions are bounded, so the image of the **energy-momentum map** looks like:



Example: the coupled angular momenta

Coupled angular momenta

- ▶ The **coupled angular momenta** is a 4-dimensional integrable Hamiltonian system with 2 degrees of freedom
- ▶ It consists of a non-trivial "coupling" of **two spin angular momenta**, $S = (S_x, S_y, S_z)$ and $N = (N_x, N_y, N_z)$.
- ▶ It appears in quantum mechanics⁵ and there are also classical and semi-classical studies
- ▶ The **classical phase space** is thus $\mathbb{S}^2 \times \mathbb{S}^2$ with symplectic form $\omega = -(R_1\omega_{\mathbb{S}^2} \oplus R_2\omega_{\mathbb{S}^2})$. We define

$$L := R_1 z_1 + R_2 z_2 \quad H := (1 - t) \frac{S_z}{|S|} + t \frac{S \cdot N}{|S||N|}$$

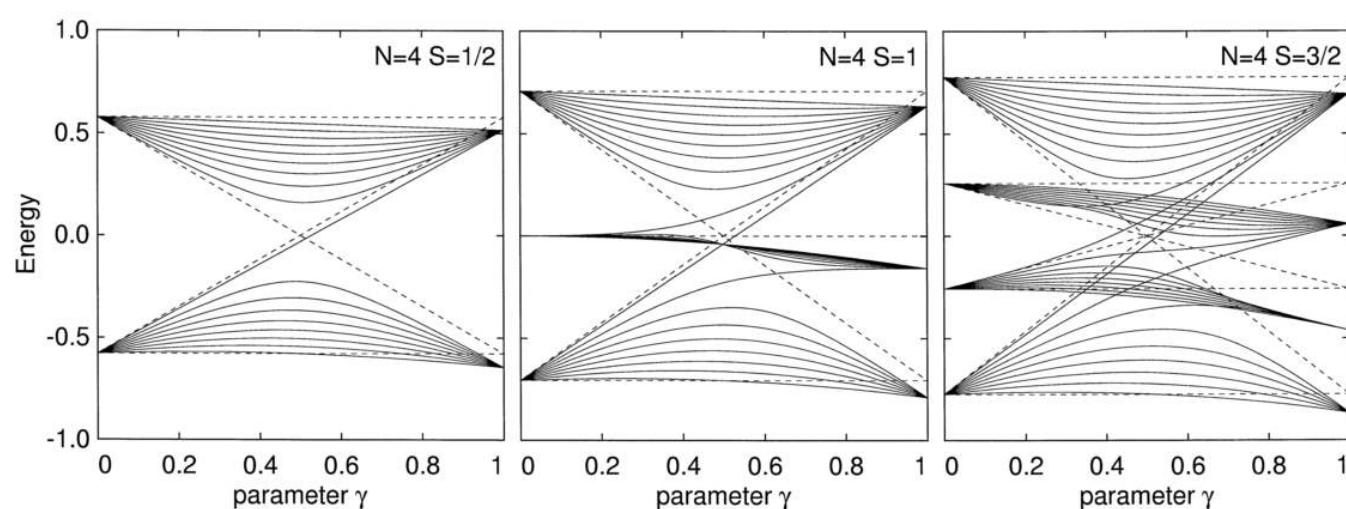
⁵ D. A. Sadovskii, B. I. Zhilinskiĭ, *Monodromy, diabolic points, and angular momentum coupling*, Phys. Lett. A, (1999)

Coupled angular momenta

- We have

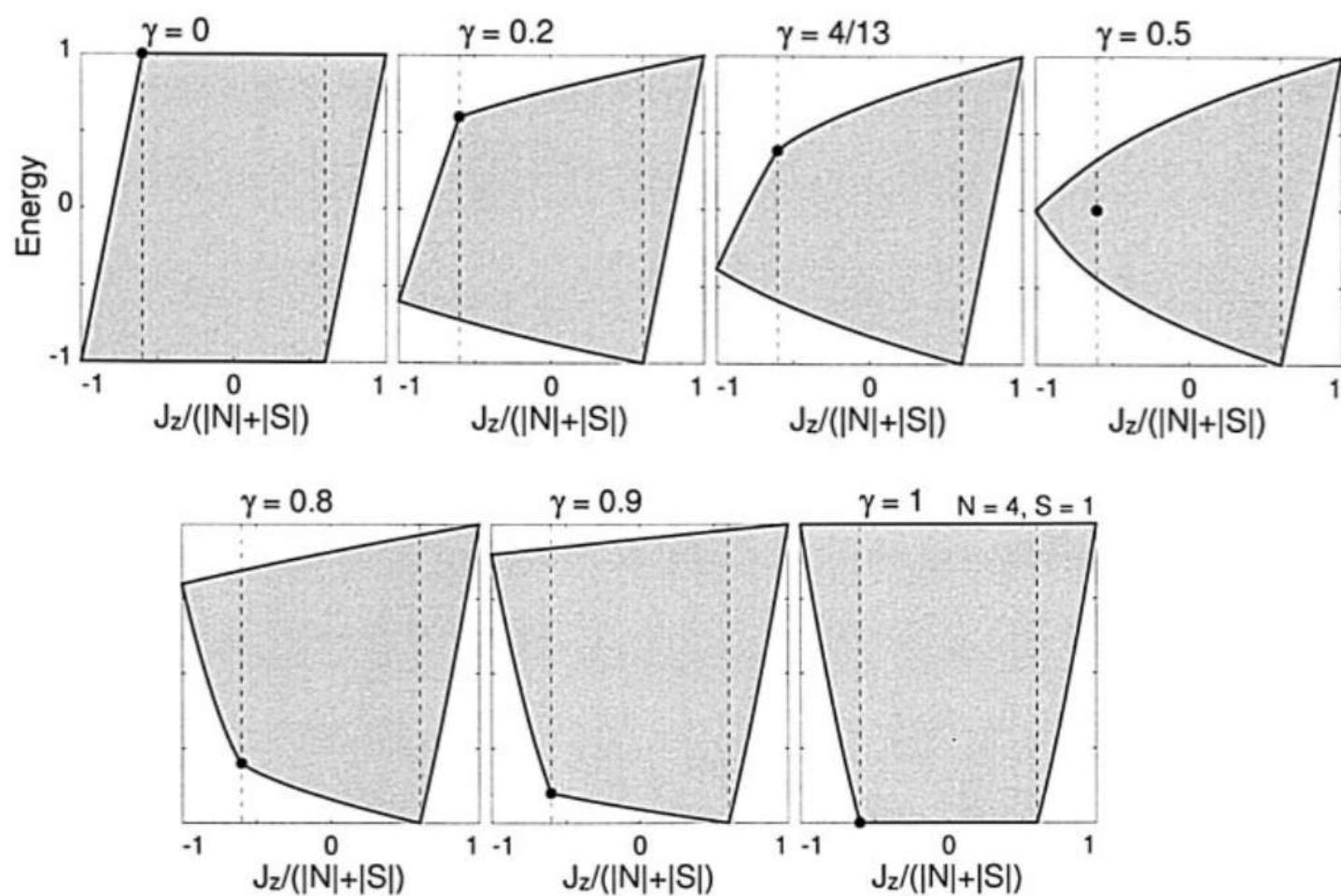
$$L := R_1 z_1 + R_2 z_2 \quad H := (1 - t) \frac{S_z}{|S|} + t \frac{S \cdot N}{|S||N|}$$

- For $t = 0$ we have only one angular spin momentum. N is free so it "generates" the degeneracy
- For $t = 1$ we have a simple angular momenta addition. We get a "multiplet" structure
- In between we have a "diabolic point"



Coupled angular momenta

L induces an \mathbb{S}^1 -action. We can see the evolution of the image of the momentum map as we move the parameter t :



Coupled angular momenta

More mathematically:

- We have $M = \mathbb{S}^2 \times \mathbb{S}^2$. In Cartesian coordinates $(x_1, y_1, z_1, x_2, y_2, z_2)$:

$$\begin{cases} L := R_1(z_1 - 1) + R_2(z_2 + 1) \\ H := (1 - t)z_1 + t(x_1x_2 + y_1y_2 + z_1z_2) + 2t - 1. \end{cases}$$

- The system has four critical points: $N \times N$, $N \times S$, $S \times N$ and $S \times S$.
- 3 of them are always elliptic-elliptic. But $N \times S$ is of focus-focus type for $t \in (t^-, t^+)$, where

$$t^\pm = \frac{R_2}{2R_2 + R_1 \mp 2\sqrt{R_1R_2}}$$

- In particular, $t^- < 1/2 < t^+$.

The symplectic classification of semi-toric systems

Classification

Pelayo and Vũ Ngọc have achieved⁶⁷ a complete 'generic' classification of semi-toric systems in terms of **five symplectic invariants**:

1. The **number of focus-focus critical points** invariant
2. The **polygon** invariant
3. The **height** invariant
4. The **twisting-index** invariant
5. The **Taylor-series** invariant

These invariants completely determine the integrable system up to global isomorphism of semi-toric systems.

⁶ Á. Pelayo, S. Vũ Ngọc, *Semitoric integrable systems on symplectic 4-manifolds*, Invent. Math., (2009)

⁷ Á. Pelayo, S. Vũ Ngọc, *Constructing integrable systems of semitoric type*, Acta Math., (2011)

Symplectic invariants

The number of focus-focus critical points invariant

The number $m_f \in \mathbb{N} \cup \{0\}$ of singularities of focus-focus type that the system has.

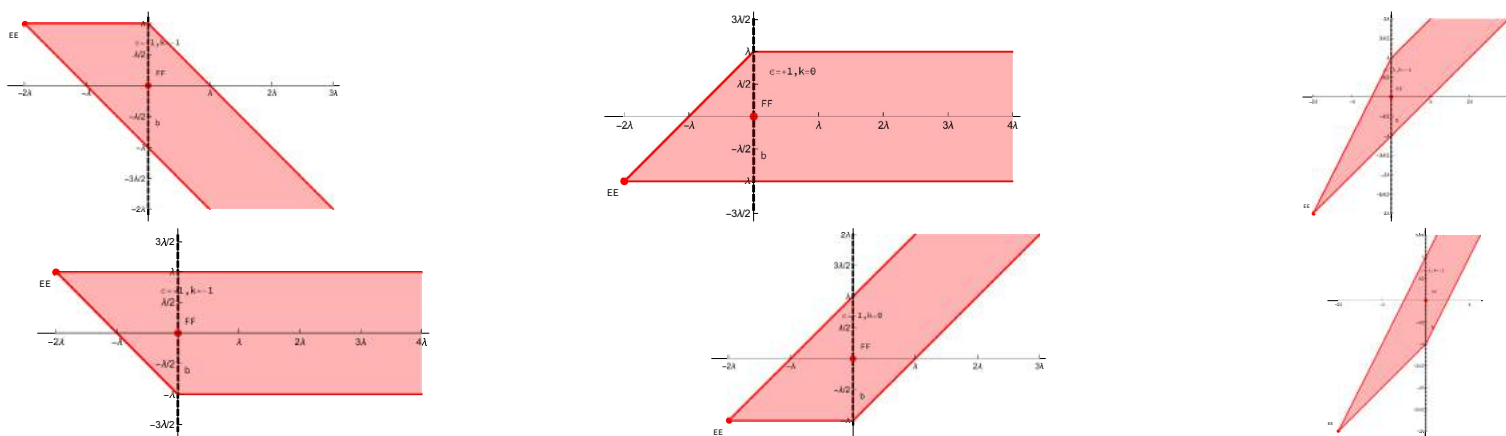
- ▶ The coupled spin-oscillator has $m_f = 1$, corresponding to the point $N \times \{0\}$.
- ▶ The singularity on $S \times \{0\}$ is of elliptic-elliptic type.

Symplectic invariants

The polygon invariant

We associate a family of simple, rational, convex polygons to a semi-toric system. There is a way to go from one polygon to the other (group action), so the invariant is the orbit of this action.

- They are a family of polygons (so more than one)
- Here we can see some of the polygons of the coupled spin-oscillator

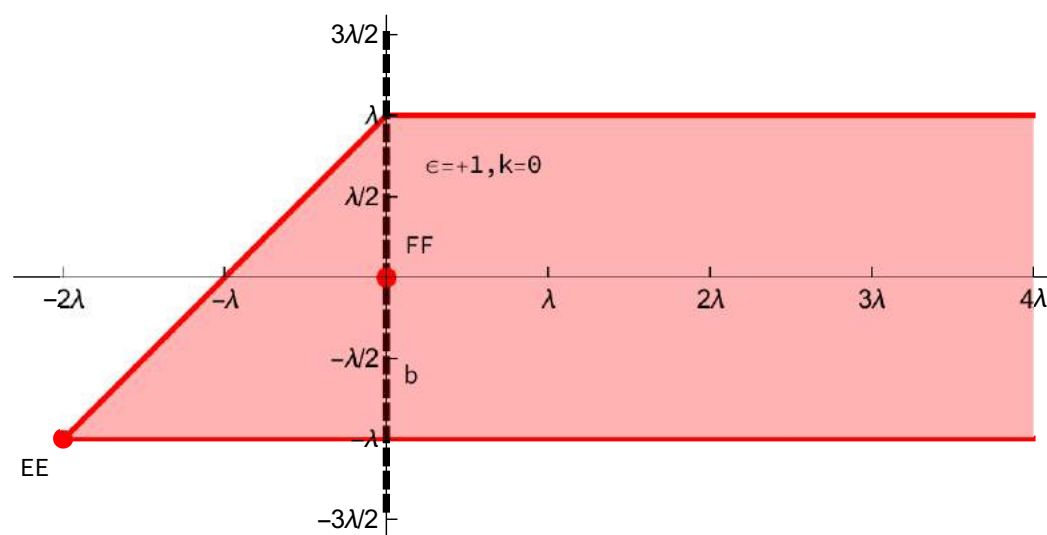


Symplectic invariants

The height invariant

Also called volume invariant, it measures the height of each focus-focus point in the polygons of the polygon invariant.

- The height invariant of the coupled spin-oscillator is 1.

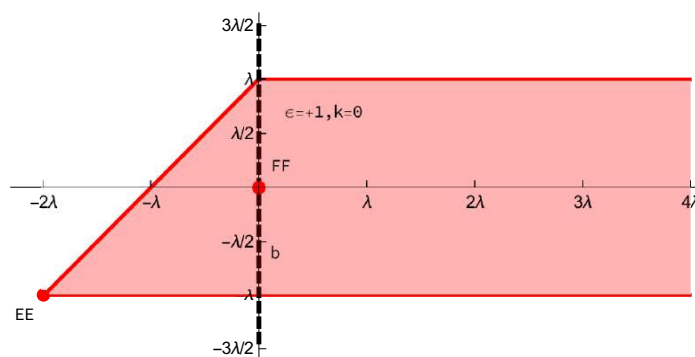


Symplectic invariants

The twisting-index invariant

It is an equivalence class of integer m_f -tuples. It quantifies the dynamical complexity of the system at a global level, involving all focus-focus points at the same time.

- For systems with one focus-focus singularity it does not carry a lot of meaning.
- For the couple spin-oscillator, this polygon carries the value 0.



Symplectic invariants

Taylor series invariant

It consists of m_f Taylor-series $(S_i)^\infty$, one per focus-focus singularity. It is a semi-global invariant of the fibration induced by (J, H) . We associate an analytic function S_i that measures how the behaviour along the critical fibre differs from “perfect logarithmic” dynamics. Its Taylor-series is the invariant.

- ▶ Non-trivial to calculate. Until recently only linear terms were known.
- ▶ For the spin-oscillator is:

$$\begin{aligned}
 S(j, l) = & (5 \log 2 + \log \lambda)j + \frac{\pi}{2}l + \frac{1}{4\lambda}jl - \frac{1}{768\lambda^2}j(34j^2 + 39l^2) \\
 & + \frac{1}{1536\lambda^3}lj(34j^2 + 23l^2) - \frac{1}{2621440\lambda^4}j(10727j^4 + 30620j^2l^2 + 13505l^4) + \dots
 \end{aligned}$$

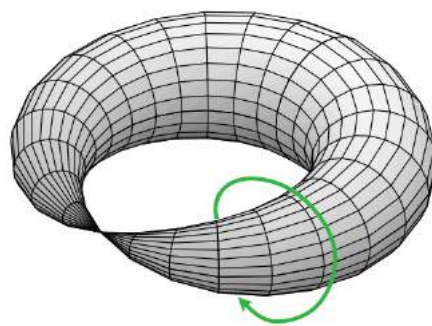
The Taylor-series invariant

Taylor-series invariant

- ▶ (M, ω, Φ) semi-toric system, $\Phi = (L, H)$ that generates foliation \mathcal{F} .
- ▶ m focus-focus critical point, $\Phi(m) = 0$, $\Phi^{-1}(0)$ critical fibre.
- ▶ Thm. Eliasson/Miranda-Zung: $\exists(x_1, y_1, x_2, y_2)$ local symplectic coordinates around m :
 - ▶ The foliation \mathcal{F} is given by connected components of $q := (q_1, q_2)$.

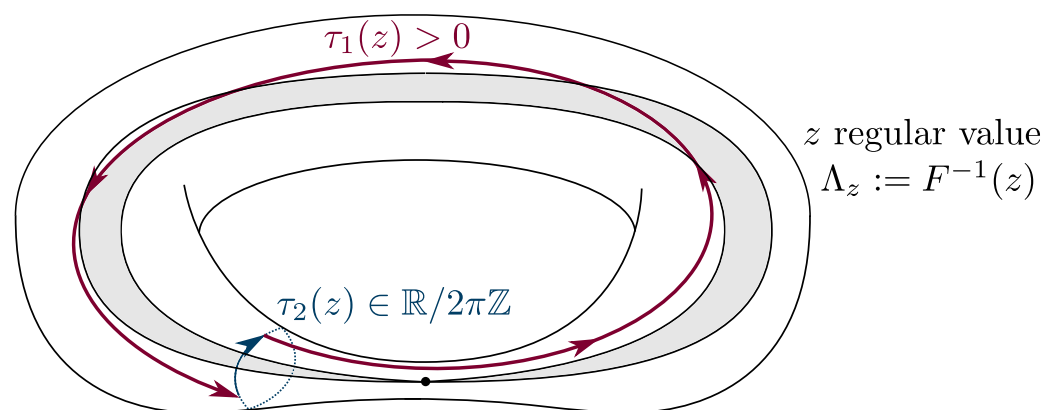
$$\begin{cases} q_1(x_1, y_1, x_2, y_2) = x_1x_2 + y_1y_2 \\ q_2(x_1, y_1, x_2, y_2) = x_1y_2 - y_1x_2 \end{cases}$$

- ▶ Near m , q_2 -orbits are 2π -periodic.
- ▶ q_1 is hyperbolic, local stable manifold is (x_2, y_2) -plane, local unstable manifold is (x_1, y_1) -plane.
- ▶ q_1 is radial, i.e. it tends towards 0 without spiraling in the unstable manifold.

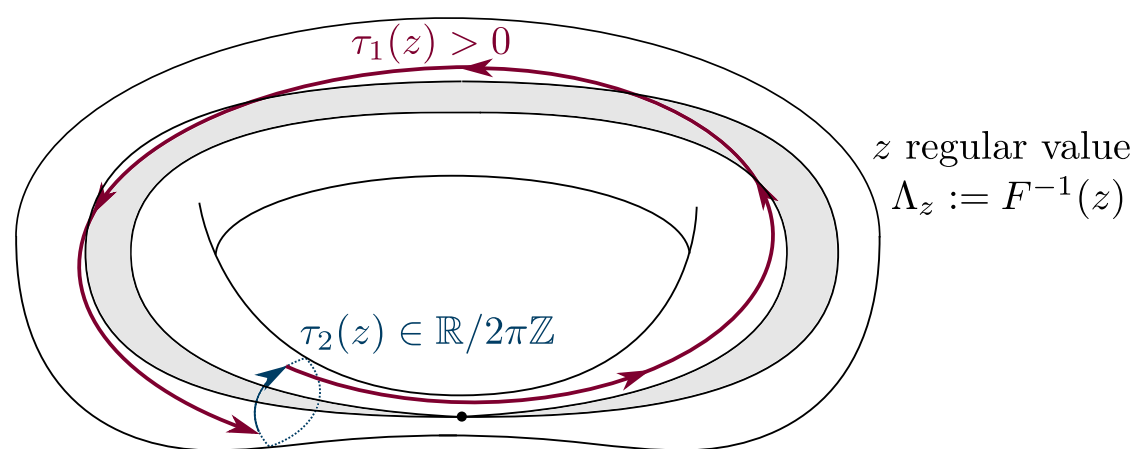


Taylor-series invariant

- ▶ $\exists \phi$ local diffeomorphism of \mathbb{R}^2 such that $q = \phi \circ \Phi$.
- ▶ We can extend to a global momentum map: $F := \phi \circ \Phi$. Locally agrees with q . We write $F := (F_1, F_2)$.
- ▶ Close to the critical point, the F_2 -orbits must be periodic, because $F_2 = q_2$.
- ▶ Define fibres $\Lambda_z := F^{-1}(z)$ with $z := z_1 + iz_2$ close to 0. In particular, $F^{-1}(0)$ singular fibre.
- ▶ Take $a \in \Lambda_z$. Follow the flows on the regular fibre: $\tau_1(z)$ along φ^{F_1} and $\tau_2(z) \in \mathbb{R}/2\pi\mathbb{Z}$ along φ^{F_2}



Taylor-series invariant



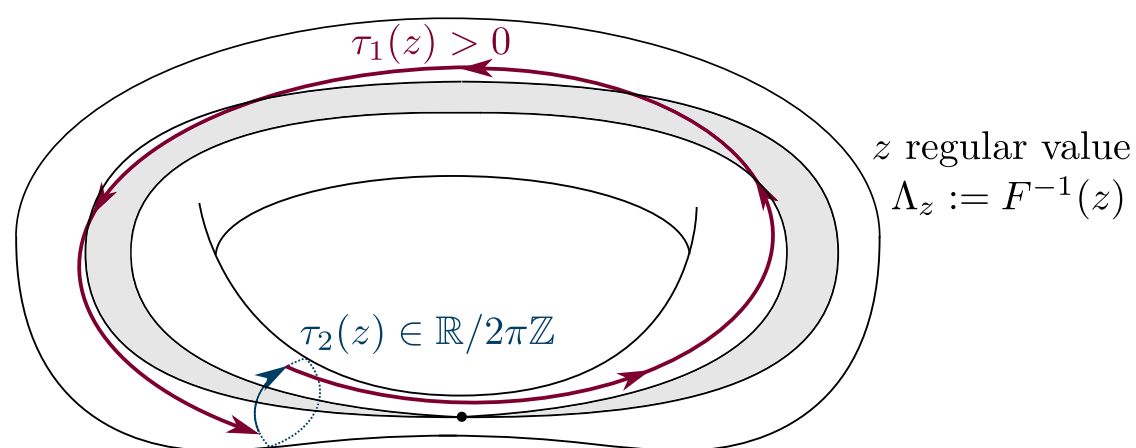
► Define

$$\begin{cases} \sigma_1(z) := \tau_1(z) + \operatorname{Re}(\ln z) \\ \sigma_2(z) := \tau_2(z) - \operatorname{Im}(\ln z) \end{cases}$$

- Then σ_1, σ_2 extend to smooth (single-valued) functions around 0
- The 1-form $\sigma := \sigma_1 dz_1 + \sigma_2 dz_2$ is closed⁸ (Vũ Ngọc)
- Let S be the only function satisfying $dS = \sigma$, $S(0) = 0$
- **Taylor series invariant** = Taylor expansion of S around 0

⁸ S. Vũ Ngọc, *On semi-global invariants for focus-focus singularities*, Topology, (2003)

Taylor-series invariant



The function S is related to the reduced action $I(z)$ of the system

- ▶ Take ϖ semi-global primitive of ω and γ_z our closed trajectory on the regular fibre
- ▶ Then the **reduced action** is $I(z) := \frac{1}{2\pi} \oint_{\gamma_z} \varpi$
- ▶ It satisfies $2\pi dI(z) = \tau_1(z)dz_1 + \tau_2(z)dz_2$
- ▶ Therefore the invariant is

$$S(z) = 2\pi I(z) - 2\pi I(0) + \operatorname{Re}(z \ln z - z)$$

Recent advances

Recent advances

Recent advances:

- ▶ Calculation of the Taylor series invariant and the twisting index invariant of the **coupled spin-oscillator**⁹ (A., Dullin, Hohloch)
- ▶ Calculation of the Taylor series invariant and the twisting index invariant of the **coupled angular momenta** depending on the different parameters¹⁰ (A., Dullin, Hohloch)
- ▶ Description of a system with **two focus-focus points**¹¹ (Hohloch, Palmer)

⁹ J. A., H. R. Dullin, S. Hohloch, *Taylor series and twisting-index invariants of coupled spin-oscillators*, arXiv:1712.06402 (2017).

¹⁰ J. A., H. R. Dullin, S. Hohloch, *Taylor-series symplectic invariant of the coupled angular momenta*, (in progress).

¹¹ S. Hohloch, J. Palmer, *A family of compact semitoric systems with two focus-focus singularities*, arXiv:1710.05746 (2017).

Coupled spin-oscillator

- We had $M = \mathbb{S}^2 \times \mathbb{R}^2$ with symplectic form $\omega = \lambda \omega_{\mathbb{S}^2} \oplus \mu \omega_{\mathbb{R}^2}$
- Functions:

$$L := \mu \frac{u^2 + v^2}{2} + \lambda(z - 1) \quad H := \frac{1}{2}(ux + vy)$$

- After some transformations, the system can be rewritten as

$$L = p_1 \quad H = \sqrt{\frac{-p_2(p_2 - p_1)(p_2 - p_1 - 2\lambda)}{2\lambda^2\mu}} \cos q_2$$

with symplectic coordinates (q_1, p_1, q_2, p_2) and symplectic form

$$\omega = dq_1 \wedge dp_1 \oplus dq_2 \wedge dp_2$$

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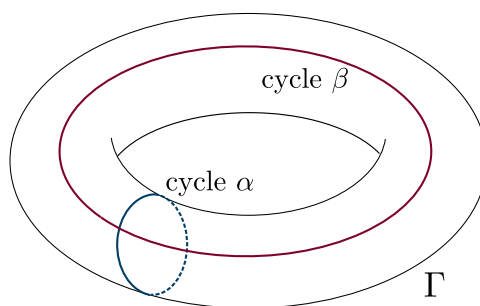
Coupled spin-oscillator

- ▶ Typical way to define **action integral**: $I(z) = \frac{1}{2\pi} \oint p \, dq$
- ▶ But requires solving a cubic equation. Better $I(z) = \frac{1}{2\pi} \oint q \, dp$
- ▶ If we integrate by parts, we get an **elliptic integral**

$$I(l, h) = \frac{1}{2\pi} \oint_{\beta} -h \left(3 + \frac{l}{p_2 - l} + \frac{l + 2\lambda}{p_2 - l - 2\lambda} \right) \frac{dp_2}{w}$$

defined on

$$\Gamma_{l,h} := \{(p_2, w) : w^2 = P(p_2)\}, \quad P(p_2) = -\frac{2}{\lambda^2 \mu} p_2(p_2 - l)(p_2 - l - 2\lambda) - 4h^2$$



Coupled spin-oscillator

- When expanding elliptic integrals, the integral along the vanishing α cycle appears in front of the logarithm. We call it **imaginary action**:

$$J(l, h) := \frac{1}{2\pi i} \oint_{\alpha} -h \left(3 + \frac{l}{p_2 - l} + \frac{l + 2\lambda}{p_2 - l - 2\lambda} \right) \frac{dp_2}{w}$$

- Since the α cycle vanishes as we approach the singularity m , we can use the **residue theorem** to expand it around m :

$$\frac{1}{\sqrt{\lambda\mu}} J(l, h) = -2h + \frac{1}{4\lambda} lh - \frac{1}{128\lambda^2} h(9l^2 + 20\lambda\mu h^2) + \dots$$

- We can invert this series to obtain a “sort of” Birkhoff normal form $h = B(j, l)$ and get everything in terms of (j, l) instead of (l, h) . The (j, l) actually correspond to the (z_1, z_2) where $z := z_1 + iz_2$.

Coupled spin oscillator

And now we have all the ingredients we need:

- We **expand** the action integral (we get rational functions)

$$\begin{aligned}
 2\pi I(l, h) = & 2\lambda\pi + \frac{\pi}{2} + l \arctan\left(\frac{l}{2\sqrt{\lambda\mu}h}\right) + J(l, h) \log\left(\frac{32\lambda}{\sqrt{l^2 + 4\lambda\mu}h^2}\right) - 2\sqrt{\lambda\mu}h \\
 & - \frac{\sqrt{\lambda\mu}}{2\lambda}lh + \frac{\sqrt{\lambda\mu}}{384\lambda^2(l^2 + 4\lambda\mu h^2)}h(63l^4 + 412\lambda\mu l^2 h^2 + 544\lambda^2\mu^2 h^4) + \dots
 \end{aligned}$$

- And now we **substitute** $h = B(j, l)$

$$\begin{aligned}
 2\pi I(j, l) = & 2\lambda\pi - j \log |z| + j + l \arg(z) \\
 & + (5 \log 2 + \log \lambda)j + \frac{\pi}{2}l + \frac{1}{4\lambda}jl - \frac{1}{768\lambda^2}j(34j^2 + 39l^2) + \dots
 \end{aligned}$$

so all rational functions transform into a well-defined Taylor-series, which is what “theory predicted”.

Coupled angular momenta

- ▶ A similar argument works for the coupled angular momenta but calculations are too complex
- ▶ Another approach: **reduced period** and **rotation number**

$$T := 2\pi \frac{\partial I}{\partial h}, \quad W = -\frac{\partial I}{\partial l}$$

- ▶ We define **imaginary reduced period** and **imaginary rotation number**

$$T^\alpha := 2\pi \frac{\partial J}{\partial h}, \quad W^\alpha = -\frac{\partial J}{\partial l}$$

- ▶ Then the derivatives of the invariant are (A., Dullin, Hohloch):

$$\frac{\partial S}{\partial j} = 2\pi \frac{T}{T^\alpha} + \ln |z|, \quad \frac{\partial S}{\partial l} = 2\pi \left(W^\alpha \frac{T}{T^\alpha} - W \right) - \arg(z)$$

System with two FF

System with two focus-focus singularities:

- ▶ Generalisation of the coupled angular momenta
- ▶ Defined on $M = \mathbb{S}^2 \times \mathbb{S}^2$ with $\omega = -(R_1\omega_{\mathbb{S}^2} \oplus R_2\omega_{\mathbb{S}^2})$, where $0 < R_1 < R_2$
- ▶ The system depends on four parameters $t := (t_1, t_2, t_3, t_4)$

$$\begin{cases} L = R_1 z_1 + R_2 z_2 \\ H = t_1 z_1 + t_2 z_2 + t_3(x_1 x_2 + y_1 y_2) + t_4 z_1 z_2 \end{cases}$$

and it is semi-toric with two focus-focus singularities for some values of t .

System with two FF

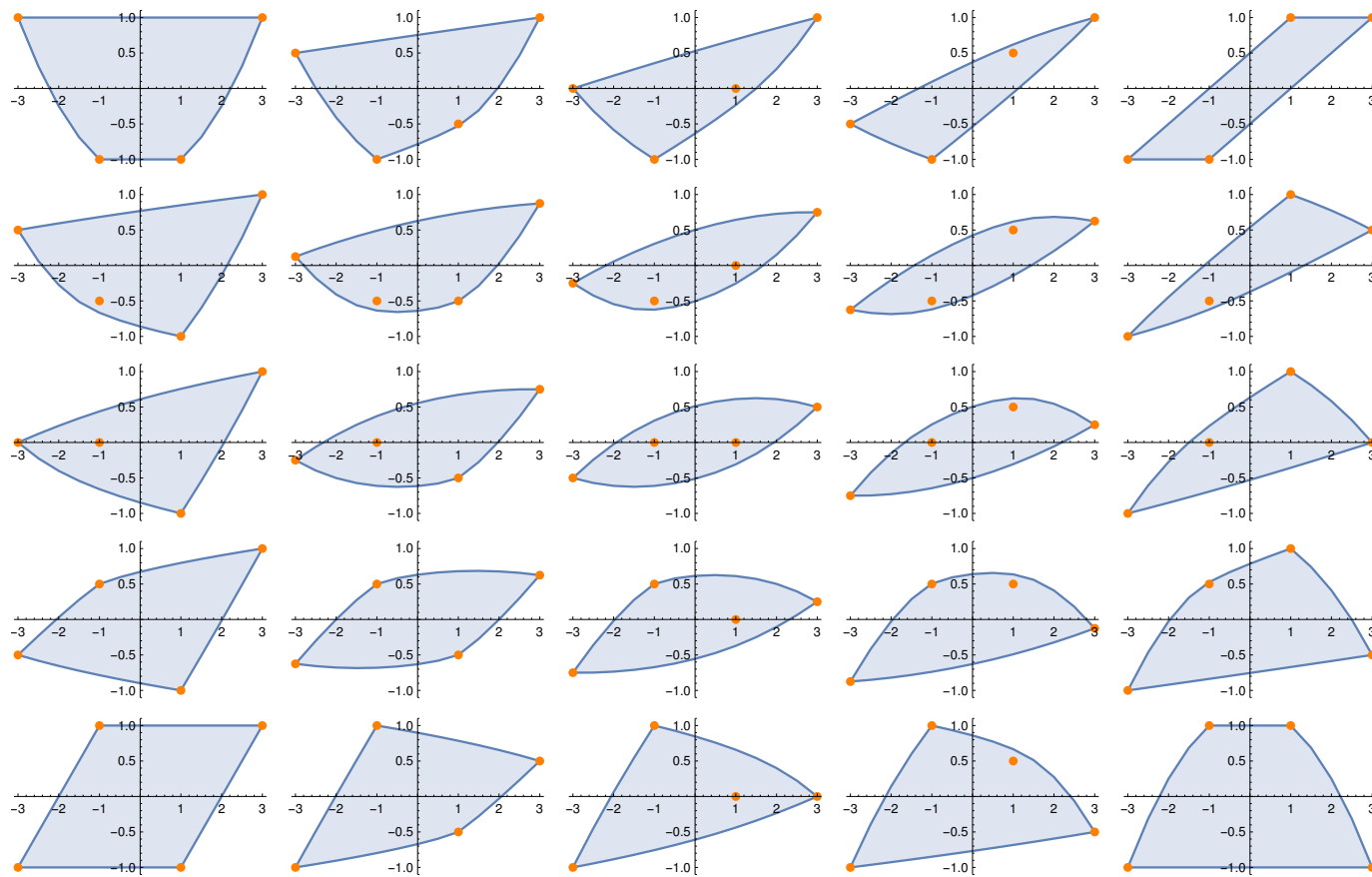
Special parameter choices with $s_1, s_2 \in [0, 1]$:

$$t_1 = s_1(1 - s_2)$$

$$t_2 = s_2(1 - s_1)$$

$$t_3 = (1 - s_1)(1 - s_2) + s_1 s_2$$

$$t_4 = (1 - s_1)(1 - s_2) - s_1 s_2$$



Grazie per l'attenzione!