Observability and controllability properties for waves

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New Trends in Control Theory and PDEs, July 2017 Piermarco Cannarsa's Birthday







E. Trélat Observability and controllability properties for waves

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Setting

- (M,g) be a smooth *d*-dimensional Riemannian manifold
- \triangle_g Laplace-Beltrami operator on *M*, associated with the metric *g*
- Ω open bounded connected subset of *M*, with a smooth boundary if $\partial \Omega \neq \emptyset$

Consider the wave equation

$$\partial_t^2 u - \triangle_g u = 0$$
 in $\mathbb{R} \times \Omega$

with Dirichlet or Neumann boundary conditions if $\partial \Omega \neq \emptyset$.

Results hereafter are valid for more general time-independent wave operators

$$\partial_t^2 - \sum_{i,j} a_{ij}(x) \partial_{x_i} \partial_{x_j} + \text{smooth lower-order terms}$$



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Observability with a time-varying domain



We have observability on Q in time T if there exists C > 0 such that

$$C\|(u(0),\partial_t u(0))\|_{H_0^1 \times L^2}^2 \leq \|\chi_Q \partial_t u\|_{L^2((0,T) \times \Omega)}^2 = \int_0^T \int_{\omega(t)} |\partial_t u(t,x)|^2 \, dx_g \, dt,$$

$$\Leftrightarrow C \| (u(0), \partial_t u(0)) \|_{L^2 \times H^{-1}}^2 \leq \| \chi_Q u \|_{L^2((0,T) \times \Omega)} \|^2 = \int_0^T \int_{\omega(t)} |u(t,x)|^2 \, dx_g \, dt$$

(Dirichlet case) for any solution *u* of the wave equation.



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Usual (static) Geometric Control Condition



Theorem (Bardos Lebeau Rauch, SICON 1992)

Take $\omega(t) \equiv \omega$ open. Under the GCC on (ω, T) :

Every geometric ray propagating in Ω , and reflecting on $\partial\Omega$ according to the optics laws, meets ω within time *T*,

and if moreover there is no ray having a contact of infinite order with $\partial \Omega$ whenever $\partial \Omega \neq \emptyset$, then we have observability on ω in time T.



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Time-dependent Geometric Control Condition

Now, $\omega(t)$ moves.

Le Rousseau Lebeau Terpolilli Trélat, APDE 2017

Take *Q* open subset of $\mathbb{R} \times \overline{\Omega}$. Under the *t*-GCC on (*Q*, *T*):

Every generalized bicharacteristic $s \mapsto (t(s), x(s), \tau(s), \xi(s))$ is such that there exists $s \in \mathbb{R}$ such that $t(s) \in (0, T)$ and $(t(s), x(s)) \in Q$,

and if moreover there is no generalized bicharacteristic having a contact of infinite order with $(0, T) \times \partial \Omega$ whenever $\partial \Omega \neq \emptyset$, then we have observability on Q in time T.

Remarks

- ID case: Castro Münch Cindea, SICON 2014.
- Motivation of the study for the Total company.



Time-dependent Geometric Control Condition

Consequences:

1. Observability with few sensors

Take Q open with Lipschitz boundary, with (Q, T) satisfying t-GCC.

Then every open subset \mathcal{V} of $[0, \mathcal{T}] \times \overline{\Omega}$ (for the topology induced by $\mathbb{R} \times M$) containing $\partial \left(Q \cap ([0,T] \times \overline{\Omega}) \right)$ is such that (\mathcal{V}, T) satisfies *t*-GCC, and thus observability holds for (\mathcal{V}, T) .





Observability and controllability properties for waves

Time-dependent Geometric Control Condition

Consequences:

2. Controllability

Under the previous assumptions, by duality, the wave equation with (time-dependent) internal control

$$\partial_t^2 u - \triangle_g u = \chi_Q f$$

is exactly controllable in $H_0^1 \times L^2$.





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Observability constant in large time

Time-dependent Geometric Control Condition

Consequences:

3. Stabilization

There exist $\mu \ge 0$ and $\nu > 0$ such that any solution of

$$\partial_t^2 u - \triangle_g u + \chi_{\omega(t)} \partial_t u = 0$$

satisfies

$$\|u(t)\|_{H_0^1}^2 + \|\partial_t u(t)\|_{L^2}^2 \leq \mu \left(\|u(0)\|_{H_0^1}^2 + \|\partial_t u(0)\|_{L^2}^2\right) e^{-\nu t}$$





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Sketch of proof

We follow the lines of the classical proof by Bardos Lebeau Rauch:

1st step: weak observability inequality

There exists C > 0 such that

$$C\|(u(0),\partial_t u(0))\|_{H^1_0 \times L^2}^2 \leq \|\chi_Q \partial_t u\|_{L^2((0,T) \times \Omega)}^2 + \|(u(0),\partial_t u(0))\|_{L^2 \times H^-}^2$$

for any solution.

Proof by contradiction + propagation of singularities for defect measures. *t*-GCC is used to prove that the QL vanishes identically.





Sketch of proof

2nd step: no invisible solution

Set of invisible solutions:

 $N_{T} = \{ v \in H^{1}((0, T) \times \Omega) \mid v \text{ wave solution} \\ \text{with } v(0) \in H^{1}_{0}, \partial_{t} v(0) \in L^{2} \text{ and } \chi_{O} \partial_{t} v = 0 \},$

equiped with the norm $\|v\|_{N_T}^2 = \|v(0)\|_{H_0^1}^2 + \|\partial_t v(0)\|_{L^2}^2$. N_T is closed.

We have $N_T = \{0\}$.

ightarrow The main simplification with respect to BLR 1992 is there.



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Sketch of proof

- Propagation of singularities + t-GCC
 ⇒ any invisible solution is smooth on (0, T) × Ω up to the boundary
 - $\partial_t^2 \triangle_g$ time-independent
- $\Rightarrow N_T \text{ invariant under } \partial_t: \quad v \in N_T \Rightarrow \partial_t v \in N_T$
- 2 weak observability
 - $\Rightarrow \ C \|v\|_{N_{T}}^{2} = C \|(v(0), \partial_{t}v(0))\|_{H_{0}^{1} \times L^{2}} \leq \|(v(0), \partial_{t}v(0))\|_{L^{2} \times H^{-1}} \quad \forall v \in N_{T}$

Since $H_0^1 \times L^2$ is compactly embedded into $L^2 \times H^{-1}$, this implies that the unit ball of N_T is compact and thus N_T is finite dimensional.

By contradiction: if $N_T \neq \{0\}$, then $\partial_t : N_T \to N_T$ has a (complex) eigenvalue λ , with eigenfunction $v \in N_T \setminus \{0\}$: $v(t, x) = e^{\lambda t}w(x) \Rightarrow (\lambda^2 - \triangle_g)w = 0$.

Take *t* s.t. $\omega(t) \neq \emptyset$. Since $\chi_Q \partial_t v = 0$ and thus $\chi_Q v = 0$, it follows that w = 0 on $\omega(t)$. By elliptic unique continuation: w = 0 on Ω , and hence v = 0. Contradiction.





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In what follows:

 $T_0(Q, \Omega) = \inf\{T > 0 \mid (Q, T) \text{ satisfies } t\text{-GCC}\}$

 \rightarrow minimal *t*-GCC time





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Example: 1D

 $M = \mathbb{R}$ (Euclidean), $\Omega = (0, 1)$

$$\omega(t) = (vt, vt + a)$$
 when $t \in (0, (1 - a)/v)$





$$T_{0}(v, a, \delta) = \begin{cases} 2(1-a)/(1+v) & \text{if } 0 \leq v < 1 \text{ and } \delta \geq 0, \\ 1-a & \text{if } v = 1 \text{ and } \delta > 0, \\ (1-a)(3v+1)/(v(1+v)) & \text{if } v \geq 1 \text{ and } \delta = 0, \\ (2(1-a)+v\delta)(1+v) & \text{if } v > 1 \text{ and } \delta > 0. \end{cases}$$



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Example: moving domain on the sphere

 $egin{aligned} &M=\Omega=S^2 ext{ (Euclidean)}\ &a\in(0,2\pi),\,arepsilon\in(0,\pi/2),\, v>0\ &\omega(t)=\{(heta,arphi)\ \mid arphiert<arepsilon,\, vt< heta< vt+a\} \end{aligned}$



Then:

 $T_0(v, a, \varepsilon) < +\infty$ except for a finite number of critical speeds v > 0. Moreover:

•
$$T_0(v, a, \varepsilon) \sim \frac{\pi - a}{v}$$
 as $v \to 0$.

• If
$$v > (2\pi - a + 2\varepsilon)/(2\varepsilon)$$
 then $T_0(v, a, \varepsilon) < \infty$.

If $v \to +\infty$ then $T_0(v, a, \varepsilon) \to \pi - 2\varepsilon$.

Besides, if $v \in \mathbb{Q}$, then there exist $a_0 > 0$ and $\varepsilon_0 > 0$ such that $T_0(v, a, \varepsilon) = +\infty$ for every $a \in (0, a_0)$ and every $\varepsilon \in (0, \varepsilon_0)$.



Observability constant in large time

Example: moving domain near the boundary of the disk

$$M = \mathbb{R}^2$$
 (Euclidean), $\Omega = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 < 1\}$

 $a \in (0, 2\pi), \varepsilon \in (0, 1)$

$$\omega(t) = \{ (r, \theta) \in [0, 1] \times \mathbb{R} \mid 1 - \varepsilon < r < 1, \ vt < \theta < vt + a \}$$



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Observability constant in large time

Example: moving domain near the boundary of the disk

$$egin{aligned} &\mathcal{T}_0(m{v},m{a},arepsilon) < +\infty, \, ext{for every} \, m{v} > (2\pi+2arepsilon-m{a})/(2arepsilon) \ &\mathcal{T}_0(m{v},m{a},arepsilon) \sim 2-2arepsilon \, ext{ as } m{v} o +\infty. \end{aligned}$$



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Observability constant in large time

Example: moving domain near the boundary of the disk

If there exists $n \in \mathbb{N} \setminus \{0, 1\}$ such that $v \sin \frac{\pi}{n} \in \pi \mathbb{Q}$, then there exist $a_0 \in (0, 2\pi)$ and $\varepsilon_0 \in (0, 1)$ such that $T_0(v, a, \varepsilon) = +\infty \quad \forall a \in (0, a_0) \quad \forall \varepsilon \in (0, \varepsilon_0).$



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Observability constant in large time

Example: moving domain near the boundary of the disk





"secular effect"





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Observability constant in large time

Example: moving domain near the boundary of the disk



Observability constant in large time

Example: moving domain near the boundary of the disk



Even if $a \simeq 2\pi$, there exist v > 1 and $\varepsilon > 0$ small s.t. *t*-GCC fails, whereas GCC would be satisfied in the static case!





Other considerations

- Example of the square... (arithmetic considerations)
- Arbitrary domain: Do there exist T > 0 and an admissible C^1 path $t \mapsto x(t)$ in Ω , with speed $\leq v$, such that (Q, T) satisfies *t*-GCC?
- observation domain or control domain on the boundary: similar results

J. Le Rousseau, G. Lebeau, P. Terpolilli, E. Trélat, Geometric control condition for the wave equation with a time-dependent domain, Anal. PDE (2017).





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Turn back to static control or observation domains.

Geometric quantity

$$g_2(\omega) = \liminf_{T \to +\infty} \underbrace{\inf_{\gamma} \frac{1}{T} \int_0^T \chi_{\omega}(\gamma(t)) dt}_{g_2^T(\omega)},$$

where γ runs over all rays.

Spectral quantity

$$g_1(\omega) = \inf_{\phi \in \mathcal{E}} \int_{\omega} \phi^2 dx,$$

where $\mathcal{E} = set$ of normalized Laplacian eigenfunctions.



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Generalized GCC

For every ω measurable, we have

$$\begin{split} g_2^{T}(\overset{\circ}{\omega}) > 0 \ \Rightarrow \ C_{T}(\bar{\omega}) \ge C_{T}(\omega) \ge C_{T}(\overset{\circ}{\omega}) > 0 \qquad \text{(usual GCC)} \\ C_{T}(\bar{\omega}) > 0 \ \Rightarrow \ g_2^{T}(\bar{\omega}) > 0 \end{split}$$

In particular, if ω has no grazing ray then $g_2^T(\overset{\circ}{\omega}) = g_2^T(\bar{\omega}) = g_2^T(\omega)$, and then we have the equivalence

$$g_2^T(\omega) > 0 \Leftrightarrow C_T(\omega) > 0$$

Time asymptotic observability constant

Given any ω measurable with no grazing ray, we have

$$\lim_{T \to +\infty} \frac{C_T(\omega)}{T} = \frac{1}{2} \min \left(g_1(\omega), g_2(\overline{\omega}) \right)$$

(compare with Lebeau's result for damped wave equations)





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Main new idea here:

• Define $C_T^{>N}(\omega)$, "high-frequency observability constant"

• Define
$$\alpha^T(\omega) = \lim_{N \to +\infty} \frac{1}{T} C_T^{>N}(\omega) = \sup_N \frac{1}{T} C_T^{>N}(\omega)$$

• Prove that
$$\lim_{T \to +\infty} \frac{C_T(\omega)}{T} = \min\left(\frac{1}{2}g_1(\omega), \limsup_{T \to +\infty} \alpha^T(\omega)\right)$$

• Prove that $C_T(\omega) > 0 \Leftrightarrow \alpha^T(\omega) > 0 \quad \forall \omega$ measurable (elementary proof by considering invisible solutions).

E. Humbert, Y. Privat, E. Trélat,

Observability properties of the homogeneous wave equation on a closed manifold, preprint (2016).

Still ongoing works using this "quantum observability constant" $\alpha^{T}(\omega)$.





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Characterization of Zoll manifolds

Known results:

Time-varying control domains

- X Hamiltonian vector field (on S^*M) of $\sqrt{\bigtriangleup}$
- $S = \frac{1}{i}L_X$
- $\Sigma = \text{closure of } \{\lambda \mu \mid \lambda, \mu \in \text{Spec}\sqrt{\Delta}\}$

Helton, Guillemin, 1977

• Spec(S) $\subset \Sigma$.

- If there exists a nonperiodic geodesic, then $\text{Spec}(S) = \mathbb{R}$, and thus $\Sigma = \mathbb{R}$.
- *M* is Zoll if and only if Σ ≠ ℝ.
 In this case, we have Σ = ^{2π}/_T ℤ, where *T* is the smallest common period.



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Characterization of Zoll manifolds

New results:

Geometric quantities

$$g_{2}(\omega) = \liminf_{T \to +\infty} \underbrace{\inf_{\gamma} \frac{1}{T} \int_{0}^{T} \chi_{\omega}(\gamma(t)) dt}_{g_{2}^{T}(\omega)}, \qquad g_{2}'(\omega) = \inf_{\gamma} \liminf_{T \to +\infty} \frac{1}{T} \int_{0}^{T} \chi_{\omega}(\gamma(t)) dt$$

where γ runs over all rays. Note that $g_2 \leqslant g_2'$.

Spectral quantities

$$g_1(\omega) = \inf_{\phi \in \mathcal{E}} \int_{\omega} \phi^2 dx, \qquad g'_1(\omega) = \inf_{\mu \in QL} \mu(\omega)$$

where $\mathcal{E} = \text{set of normalized Laplacian eigenfunctions, and } QL = \text{quantum limits. Note that } g_1(\omega) \leq g'_1(\omega) \text{ for any closed } \omega.$

For γ *T*-periodic ray on *M*: Dirac measure $\delta_{\gamma}(f) = \frac{1}{T} \int_{0}^{T} f(\gamma(t)) dt \quad \forall f \in C^{0}(M)$.



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Characterization of Zoll manifolds

New results:

Humbert Privat Trélat, ongoing

- *M* Zoll and $\delta_{\gamma} \in QL \quad \forall \gamma \text{ periodic geod.} \Leftrightarrow g_1(\omega) \leqslant g_2(\omega) \quad \forall \omega \text{ closed}$
- *M* Zoll \Leftrightarrow $g_2(\omega) = g'_2(\omega) \quad \forall \omega$ closed

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ightarrow "Zoll defect" Z(\omega) = g_2'(\omega) - g_2(\omega)
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- M Zoll, two-point homogeneous and δ_γ ∈ QL ∀γ periodic geod. ⇒ QL = I.
- Spectral gap $\Rightarrow M$ Zoll, $\delta_{\gamma} \in QL$ $\forall \gamma$ periodic geod. $(g_1(\omega) \leqslant) g'_1(\omega) \leqslant g_2(\bar{\omega}) \quad \forall \omega$ measurable

(cf also Macia)

Uniformly locally finite spectrum (i.e., ∃ℓ > 0 and m∈ N* s.t. the intersection of the spectrum with any interval of length ℓ has at most m distinct elements)
 ⇒ M Zoll, and ∀γ geodesic ∃μ ∈ QL s.t. μ(γ(·)) > 0.

"Zollditch" conjecture: $QL = \mathcal{I} \Rightarrow M$ Zoll







Observability constant in large time

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Sufficient condition for Schrödinger internal observability

New results:

$$g_2'(\omega) > 0 \Rightarrow C_T^{
m Schrod}(\omega) > 0$$

- More general than the usual GCC condition $g_2(\omega) > 0$
- Not a necessary condition: M = T²
- actually, $C_T^{\text{Schrod}}(\omega) > 0 \Leftrightarrow \alpha^{T, \text{Schrod}}(\omega) > 0$, and $\alpha^{T, \text{Schrod}}(\omega) \ge g'_2(\omega) \ge g_2(\omega)$

As a corollary:

If *M* is not Zoll, then $\forall T > 0 \quad \exists \omega \text{ open s.t. } C_T^{\text{wave}}(\omega) = 0 \text{ and } C_T^{\text{Schrod}}(\omega) > 0$

E. Humbert, Y. Privat, E. Trélat, ongoing.









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Microlocal interpretation

$$g_2^{\mathsf{T}}(a) = \inf_{z \in S^*M} \frac{1}{\mathsf{T}} \int_0^{\mathsf{T}} a \circ \varphi_t(z) \, dt = \inf_{z \in S^*M} \bar{a}_{\mathsf{T}}(z) \qquad \forall a \in L^{\infty}(S^*M, \mu_L)$$

$$g_2(a) = \liminf_{T \to +\infty} \underbrace{\inf_{z \in S^*M} \frac{1}{T} \int_0^T a \circ \varphi_t(z) dt}_{g_2^T(a)} = \liminf_{T \to +\infty} \inf_{z \in S^*M} \bar{a}_T(z)$$

$$g_{2}'(a) = \inf_{z \in S^{*}M} \liminf_{T \to +\infty} \frac{1}{T} \int_{0}^{T} a \circ \varphi_{t}(z) dt = \inf_{z \in S^{*}M} \liminf_{T \to +\infty} \bar{a}_{T}(z)$$





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Microlocal interpretation

$$a_{t} = a \circ \varphi_{t} = \sigma_{P}(A_{t}) \quad \text{with} \quad A_{t} = e^{-it\sqrt{\Delta}}Ae^{it\sqrt{\Delta}}, \quad A = \operatorname{Op}(a) \in \Psi^{0}(M)$$

$$\bar{a}_{T} = \sigma_{P}(\bar{A}_{T}) \text{ with } \bar{A}_{T} = \frac{1}{T} \int_{0}^{T} A_{t} dt = \frac{1}{T} \int_{0}^{T} e^{-it\sqrt{\Delta}}Ae^{it\sqrt{\Delta}} dt.$$
Set $f_{T}(t) = ie^{iTt/2}\operatorname{sinc}(Tt/2)$, we have $\hat{f}_{T}(t) = \frac{1}{T}\chi_{[0,T]}(t)$. Then

$$g_{2}^{T}(a) = \inf_{z \in S^{*}M} \frac{1}{T} \int_{0}^{T} a \circ e^{tX}(z) dt = \inf_{z \in S^{*}M} \int_{R} \hat{f}_{T}(t)e^{itS}a dt (z) = \inf_{T} f_{T}(S)a$$

$$g_{2}'(a) = \inf_{S^{*}M} \liminf_{T \to +\infty} f_{T}(S)a = \inf_{Q_{0}} Q_{0} = eigenprojection onto ker S)$$

$$C_{T}(a) = \inf_{\|y\|=1} \langle \bar{A}_{T}(a)y, y \rangle = \inf_{\|y\|=1} \langle A_{f}y, y \rangle \quad \text{(half-waves)}$$



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